

Z86C33/C43

CMOS Z8[®] MCU Consumer Controller Processor

FEATURES

| Device | ROM (KB) | RAM* (Bytes) | Speed (MHz) |
|--------|-------------|-----------------|----------------|
| Z86C33 | 4 | 237 | 12, 16 |
| Z86C43 | 4 | 236 | 12, 16 |
| | 4 | 230 | |

Note: *General-Purpose

- 40-Pin DIP, 44-Pin PLCC and LQFP Packages (C43) 28-Pin DIP, 28-Pin SOIC, 28-Pin PLCC (C33)
- 3.0- to 5.5-Volt Operating Range
- Clock Free Watch-Dog Timer (WDT) Reset
- -40°C to +105°C Operating Range
- Expanded Register File (ERF)

- 32 Input/Output Lines (C43)
 24 Input/Output Lines (C33)
- Vectored, Prioritized Interrupts with Programmable Polarity
- Two Analog Comparators
- Two Programmable 8-Bit Counter/Timers, Each with Two 6-Bit Programmable Prescaler
- Watch-Dog Timer (WDT)/Power-On Reset (POR)
- On-Chip Oscillator that Accepts a Crystal, Ceramic Resonator, LC, RC, or External Clock
- RAM and ROM Protect

GENERAL DESCRIPTION

The Z86C33/C43 Consumer Controller Processor (CCPTM) is a member of Zilog's Z8[®] MCU single-chip family with enhanced wake-up circuitry, programmable Watch-Dog Timers (WDT), and low-noise/EMI options. These enhancements result in a more efficient, cost-effective design and provide the user with increased design flexibility over the standard Z8 microcontroller core. This low-power consumption CMOS microcontroller offers fast execution, efficient use of memory, sophisticated interrupts, input/output bit manipulation capabilities, and easy hardware/software system expansion.

The Z86C33/C43 features an Expanded Register File (ERF) to allow access to register-mapped peripheral and I/O circuits. Four basic address spaces are available to support this wide range of configurations: Program Memory, Register File, Data Memory, and ERF. The Register File is composed of 236 bytes of general-purpose registers, four I/O port registers, and 15 control and status registers. The ERF consists of three control registers. For applications demanding powerful I/O capabilities, the Z86C33 provides 24 pins, and the Z86C43 provides 32 pins dedicated to input and output. These lines are configurable under software control to provide timing, status signals, parallel I/O with or without handshake, and address/data bus for interfacing external memory.

To unburden the system from coping with real-time tasks such as counting/timing and data communication, the Z86C33/C43 offers two on-chip counter/timers with a large number of user-selectable modes.

With ROM/ROMIess selectivity, the Z86C43 provides both external memory and pre-programmed ROM, which enables this Z8[®] MCU to be used in high-volume applications, or where code flexibility is required.

GENERAL DESCRIPTION (Continued)

Notes: All signals with a preceding front slash, "/", are active Low. For example, B//W (WORD is active Low); /B/W (BYTE is active Low, only).

Power connections follow conventional descriptions below:

| Connection | Circuit | Device |
|------------|-----------------|-----------------|
| Power | V _{CC} | V _{DD} |
| Ground | GND | V _{SS} |

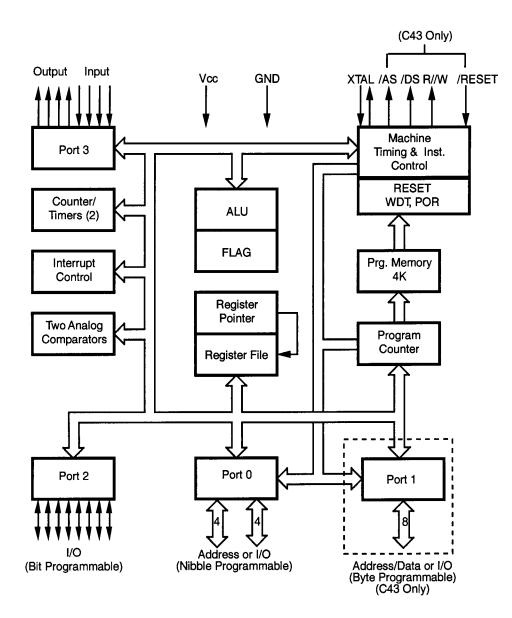


Figure 1. Functional Block Diagram

PIN DESCRIPTION

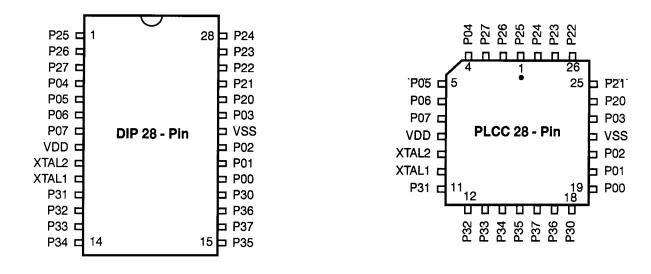


Figure 2. 28-Pin DIP/SOIC Pin Configuration

Figure 3. 28-Pin PLCC Pin Configuration

| Pin # | Symbol | Function | Direction |
|-------|-----------------|------------------------|--------------|
| 1-3 | P25-27 | Port 2, Pins 5,6,7 | In/Output |
| 4-7 | P04-07 | Port 0, Pins 4,5,6,7 | In/Output |
| 8 | V _{DD} | Power Supply | |
| 9 | XTAL2 | Crystal Oscillator | Output |
| 10 | XTAL1 | Crystal Oscillator | Input |
| 11-13 | P31-33 | Port 3, Pins 1,2,3 | Fixed Input |
| 14-15 | P34-35 | Port 3, Pins 4,5 | Fixed Output |
| 16 | P37 | Port 3, Pin 7 | Fixed Output |
| 17 | P36 | Port 3, Pin 6 | Fixed Output |
| 18 | P30 | Port 3, Pin 0 | Fixed Input |
| 19-21 | P00-02 | Port 0, Pins 0,1,2 | In/Output |
| 22 | V _{SS} | Ground | |
| 23 | P03 | Port 0, Pin 3 | In/Output |
| 24-28 | P20-24 | Port 2, Pins 0,1,2,3,4 | In/Output |

Table 1. 28-Pin DIP/SOIC/PLCC Pin Identification

PIN DESCRIPTION (Continued)

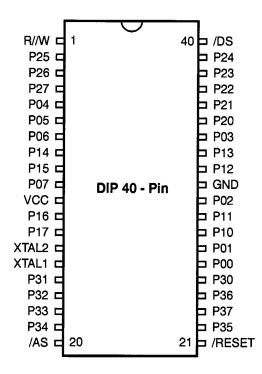




Table 2. 40-Pin Dual-In-Line Package PinIdentification

Table 2. 40-Pin Dual-In-Line Package Pin Identification

| Pin # | Symbol | Function | Direction |
|-------|-----------------|------------------------------|-----------|
| 1 | R//W | Read/Write | Output |
| 2-4 | P25-27 | Port 2, Pins 5,6,7 | In/Output |
| 5-7 | P04-06 | Port 0, Pins 4,5,6 | In/Output |
| 8-9 | P14-15 | Port 1, Pins 4,5 | In/Output |
| 10 | P07 | Port 0, Pin 7 | In/Output |
| 11 | V _{CC} | Power Supply | |
| 12-13 | P16-17 | Port 1, Pins 6,7 | In/Output |
| 14 | XTAL2 | Crystal, Oscillator Clock | Output |
| 15 | XTAL1 | Crystal, Oscillator Clock | Input |
| 16-18 | P31-33 | Port 3, Pins 1,2,3 | Input |
| 19 | P34 | Port 3, Pin 4 | Output |
| 20 | /AS | Address Strobe | Output |

| Pin # | Symbol | Function | Direction |
|-------|--------|-----------------------|-----------|
| 21 | /RESET | Reset | Input |
| 22 | P35 | Port 3, Pin 5 | Output |
| 23 | P37 | Port 3, Pin 7 | Output |
| 24 | P36 | Port 3, Pin 6 | Output |
| 25 | P30 | Port 3, Pin 0 | Input |
| 26-27 | P00-01 | Port 0, Pin 0,1 | In/Output |
| 28-29 | P10-11 | Port 1, Pin 0,1 | In/Output |
| 30 | P02 | Port 0, Pin 2 | In/Output |
| 31 | GND | Ground | |
| 32-33 | P12-13 | Port 1, Pin 2,3 | In/Output |
| 34 | P03 | Port 0, Pin 3 | In/Output |
| 35-39 | P20-24 | Port 2, Pin 0,1,2,3,4 | In/Output |
| 40 | /DS | Data Strobe | Output |
| | | | |

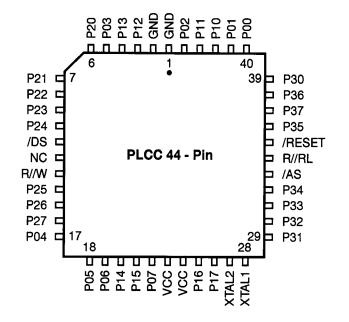




Table 3. 44-Pin PLCC Pin Identification

Table 3. 44-Pin PLCC Pin Identification

| Pin # | Symbol | Function | Direction | Pin # | Symbol | Function | Direction |
|-------|-----------------|------------------------|----------------------------------|-------|--------|----------------------------|-----------|
| 1-2 | GND | Ground | | 27 | XTAL2 | Crystal, Oscillator Clock | Output |
| 3-4 | P12-13 | Port 1, Pins 2,3 | In/Output | 28 | XTAL1 | Crystal, Oscillator Clock | Input |
| 5 | P03 | Port 0, Pin 3 | In/Output | 29-31 | P31-33 | Port 3, Pins 1,2,3 | Input |
| 6-10 | P20-24 | Port 2, Pins 0,1,2,3,4 | Port 2, Pins 0,1,2,3,4 In/Output | | P34 | Port 3, Pin 4 | Output |
| 11 | /DS | Data Strobe | Data Strobe Output | | /AS | Address Strobe | Output |
| 12 | N/C | Not Connected | | 34 | R//RL | ROM/ROMIess Control | Input |
| 13 | R//W | Read/Write | Output | 35 | /RESET | Reset | Input |
| 14-16 | P25-27 | Port 2, Pins 5,6,7 | In/Output | 36 | P35 | Port 3, Pin 5 | Output |
| 17-19 | P04-06 | Port 0, Pins 4,5,6 | In/Output | 37 | P37 | Port 3, Pin 7 | Output |
| 20-21 | P14-15 | Port 1, Pins 4,5 | In/Output | 38 | P36 | Port 3, Pin 6 | Output |
| 22 | P07 | Port 0, Pin 7 | In/Output | 39 | P30 | Port 3, Pin 0 | Input |
| 23,24 | V _{CC} | Power Supply | | 40-41 | P00-01 | Port 0, Pins 0,1 | In/Output |
| 25-26 | P16-17 | Port 1, Pins 6,7 | In/Output | 42-43 | P10-11 | Port 1, Pins 0,1 | In/Output |
| | | | · | 44 | P02 | Port 0, Pin 2 | In/Output |

PIN DESCRIPTION (Continued)

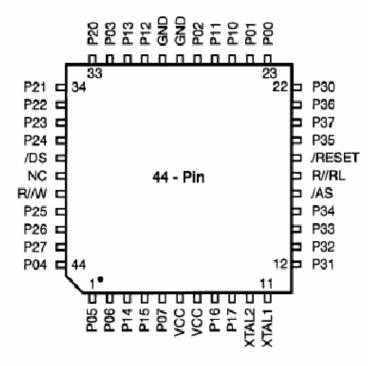




Table 4. 44-Pin LQFP Pin Identification

| Pin # | Symbol | Function | Direction |
|-------|-----------------|----------------------------|-----------|
| 1-2 | P05-06 | Port 0, Pins 5,6 | In/Output |
| 3-4 | P14-15 | Port 1, Pins 4,5 | In/Output |
| 5 | P07 | Port 0, Pin 7 | In/Output |
| 6-7 | V _{CC} | Power Supply | |
| 8-9 | P16-17 | Port 1 Pins 6,7 | In/Output |
| 10 | XTAL2 | Crystal, Oscillator Clock | Output |
| 11 | XTAL1 | Crystal, Oscillator Clock | Input |
| 12-14 | P31-33 | Port 3, Pins 1,2,3 | Input |
| 15 | P34 | Port 3, Pin 4 | Output |
| 16 | /AS | Address Strobe | Output |
| 17 | R//RL | ROM/ROMIess Control | Input |
| 18 | /RESET | Reset | Input |
| 19 | P35 | Port 3, Pin 5 | Output |
| 20 | P37 | Port 3, Pin 7 | Output |
| | | | |

Table 4. 44-Pin LQFP Pin Identification

| Pin # | Symbol | Function | Direction |
|-------|--------|------------------------|-----------|
| 21 | P36 | Port 3, Pin 6 | Output |
| 22 | P30 | Port 3, Pin 0 | Input |
| 23-24 | P00-01 | Port 0, Pins 0,1 | In/Output |
| 25-26 | P10-11 | Port 1, Pins 0,1 | In/Output |
| 27 | P02 | Port 0, Pin 2 | In/Output |
| 28-29 | GND | Ground | |
| 30-31 | P12-13 | Port 1, Pins 2,3 | In/Output |
| 32 | P03 | Port 0, Pin 3 | In/Output |
| 33-37 | P20-24 | Port 2, Pins 0,1,2,3,4 | In/Output |
| 38 | /DS | Data Strobe | Output |
| 39 | N/C | Not Connected | |
| 40 | R//W | Read/Write | Output |
| 41-43 | P25-27 | Port 2, Pins 5,6,7 | In/Output |
| 44 | P04 | Port 0, Pin 4 | In/Output |
| | | | |

ABSOLUTE MAXIMUM RATINGS

| Parameter | Min | Max | Units | Notes |
|--|------|--------------------|-------|----------|
| Ambient Temperature under Bias | -40 | +105 | С | |
| Storage Temperature | -65 | +150 | С | |
| Voltage on any Pin with Respect to V _{SS} | -0.6 | +7 | V | 1 |
| Voltage on V _{DD} Pin with Respect to V _{SS} | -0.3 | +7 | V | |
| Voltage on XTAL1 and /RESET Pins with Respect to V _{SS} | -0.6 | V _{DD} +1 | V | 2 |
| Total Power Dissipation | | 1.21 | W | |
| Maximum Allowable Current out of V _{SS} | | 220 | mA | 2· ***** |
| Maximum Allowable Current into V _{DD} | | 180 | mA | 1.1.20 |
| Maximum Allowable Current into an Input Pin | -600 | +600 | μA | 3 |
| Maximum Allowable Current into an Open-Drain Pin | -600 | +600 | μA | 4 |
| Maximum Allowable Output Current Sinked by Any I/O Pin | | 25 | mA | |
| Maximum Allowable Output Current Sourced by Any I/O Pin | | 25 | mA | · |

Notes:

1. This applies to all pins except XTAL pins and where otherwise noted.

2. There is no input protection diode from pin to V_{DD} and current into pin is limited to $\pm 600~\mu\text{A}$

3. This excludes XTAL pins.

4. Device pin is not atan output Low state.

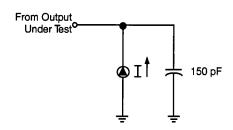
Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period may affect device reliability. Total power dissipation should not exceed 1.21 W for the package. Power dissipation is calculated as follows:

Total Power Dissipation = $V_{DD} \times [I_{DD} - (\text{sum of } I_{OH})]$

- + sum of [$(V_{DD} V_{OH}) \times I_{OH}$]
- + sum of $(V_{0L} \times I_{0L})$

STANDARD TEST CONDITIONS

The characteristics listed below apply for standard test conditions as noted. All voltages are referenced to GND. Positive current flows into the referenced pin (see Figure 7.)





CAPACITANCE

 $T_A = 25^{\circ}C$, $V_{CC} = GND = 0V$, f = 1.0 MHz, Unmeasured pins to GND

| Parameter | Min | Max | | |
|--------------------|-----|-------|--|--|
| Input capacitance | 0 | 12 pF | | |
| Output capacitance | 0 | 12 pF | | |
| I/O capacitance | 0 | 12 pF | | |

DC ELECTRICAL CHARACTERISTICS

| | | V _{cc} | | : 0° C -70°C | | -40°C 105°C | Trustant (4) | | | |
|------------------|-----------------------------|-----------------|----------------------|----------------------|---------------------------------------|----------------------|-----------------------|-------|--|-------|
| Sym | Parameter | Note [3] | | Max | Min | Max | Typical [1] @ 25°C | Units | Conditions | Notes |
| V _{CH} | Clock Input High Voltage | 3.0V | 0.7 V _{CC} | V _{CC} +0.3 | 0.7 V _{CC} | V _{CC} +0.3 | 1.8 | V | Driven by External Clock Generator | |
| | | 5.5V | 0.7 V _{CC} | V _{CC} +0.3 | 0.7 V _{CC} | V _{CC} +0.3 | 2.6 | V | Driven by External Clock Generator | |
| V _{CL} | Clock Input Low Voltage | 3.0V | GND-0.3 | 0.2 V _{CC} | GND-0.3 | 0.2 V _{CC} | 1.2 | V | Driven by External Clock Generator | |
| | | 5.5V | GND-0.3 | 0.2 V _{CC} | GND-0.3 | 0.2 V _{CC} | 2.1 | V | Driven by External Clock Generator | |
| VIH | Input High | 3.0V | 0.7 V _{CC} | V _{CC} +0.3 | 0.7 V _{CC} | V _{CC} +0.3 | 1.8 | V | | |
| | Voltage | 5.5V | 0.7 V _{CC} | V _{CC} +0.3 | 0.7 V _{CC} | V _{CC} +0.3 | 2.6 | V | ····· | |
| VIL | Input Low | 3.0V | GND-0.3 | 0.2 V _{CC} | GND-0.3 | 0.2 V _{CC} | 1.1 | V | | |
| | Voltage | 5.5V | GND-0.3 | 0.2 V _{CC} | GND-0.3 | 0.2 V _{CC} | 1.6 | V | | |
| V _{OH1} | Output High | 3.0V | V _{CC} -0.4 | | V _{CC} -0.4 | | 3.1 | V | I _{OH} = -2.0 mA | 8 |
| | Voltage | 5.5V | V _{CC} -0.4 | | V _{CC} -0.4 | | 4.8 | V | I _{OH} = -2.0 mA | 8 |
| V _{OL1} | Output Low Voltage | 3.0V | | 0.6 | | 0.6 | 0.2 | V | $I_{OL} = +4.0 \text{ mA}$ | 8 |
| | | 5.5V | | 0.4 | ······ | 0.4 | 0.1 | V | $I_{OL} = +4.0 \text{ mA}$ | |
| V _{OL2} | Output Low Voltage | 3.0V | | 1.2 | | 1.2 | 0.3 | V | I _{OL} = +6 mA | 8 |
| | | 5.5V | | 1.2 | | 1.2 | 0.4 | V | I _{OL} = +12 mA | 8 |
| V _{RH} | Reset Input High Voltage | 3.0V | .8 V _{CC} | V _{CC} | .8 V _{CC} | V _{CC} | 1.8 | V | | 13 |
| | | 5.5V | .8 V _{CC} | V _{CC} | .8 V _{CC} | V _{CC} | 2.6 | V | | 13 |
| V _{RI} | Reset Input Low Voltage | 3.0V | GND-0.3 | 0.2 V _{CC} | GND-0.3 | 0.2 V _{CC} | 1.1 | V | | 13 |
| | | 5.5V | GND-0.3 | 0.2 V _{CC} | GND-0.3 | 0.2 V _{CC} | 1.6 | V | | 13 |
| V _{OLR} | Reset | 3.0V | | 0.6 | 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 | 0.6 | 0.3 | V | I _{OL} = +1.0 mA | 13 |
| | Output Low Voltage | 5.5V | | 0.6 | | 0.6 | 0.3 | V | l _{OL} = +1.0 mA | 13 |
| VOFFSET | Comparator | 3.0V | | 25 | | 25 | 10 | mV | | 10 |
| | Input Offset Voltage | 5.5V | | 25 | | 25 | 10 | mV | | 10 |
| Ι _{ΙL} | Input | 3.0V | -1 | 2 | -1 | 2 | 0.004 | μA | $V_{IN} = 0V, V_{CC}$ | |
| | Leakage | 5.5V | -1 | 2 | -1 | 2 | 0.004 | μA | $V_{IN} = 0V, V_{CC}$ | |
| I _{OL} | Output | 3.0V | -1 | 1 | -1 | 2 | 0.004 | | $V_{IN} = 0V, V_{CC}$ | |
| | Leakage | 5.5V | -1 | 1 | -1 | 2 | 0.004 | | $V_{IN} = 0V, V_{CC}$ | |
| IIR | Reset Input | 3.0V | -20 | -130 | -18 | -130 | -60 | μA | | |
| | Current | 5.5V | -20 | -180 | -18 | -180 | -85 | μA | | |
| | Supply | 3.0V | | 20 | | 20 | 7 | | @ 16 MHz | 4 |
| | Current | 5.5V | | 25 | | 25 | 20 | | @ 16 MHz | 4 |
| | | 3.0V | | 15 | | 15 | 5 | | @ 12 MHz | 4 |
| | | 5.5V | | 20 | | 20 | 15 | mA | @ 12 MHz | 4 |

DC ELECTRICAL CHARACTERISTICS (Continued)

| Sym | | V _{cc} | | = 0° C +70°C | | =40°C +105°C | - | | | |
|------------------|--------------------------------------|-----------------|-----|-----------------------|------------------------|-----------------------|-----------------------|-------|--|--------------|
| | Parameter | Note [3] | Min | Max | Min | Max | Typical [1] @ 25°C | Units | Conditions | Notes |
| I _{CC1} | Standby Current | 3.0V | | 4.5 | | 4.5 | 2.0 | mA | V _{IN} = 0V, V _{CC} @ 16 MHz | 4 |
| | (HALT Mode) | 5.5V | | 8 | - 11 / 2 · · · · · · · | 8 | 3.7 | mA | V _{IN} = 0V, V _{CC} @ 16 MHz | 4 |
| | | 3.0V | | 3.4 | | 3.4 | 1.5 | mA | Clock Divide-by 16 @ 16 MHz | -4 |
| | | 5.5V | | 7.0 | | 7.0 | 2.9 | mA | Clock Divide-by 16 @ 16 MHz | -4 |
| I _{CC2} | Standby Current (STOP Mode) | 3.0V | | 8 | | 8 | 2 | μA | V _{IN} = 0V, V _{CC} WDT is not Running | 6,11 |
| | | 5.5V | | 10 | | 10 | 4 | μA | $V_{IN} = 0V, V_{CC}$ WDT is not Running | 6,11 |
| | | 3.0V | | 500 | | 600 | 310 | μA | V _{IN} = 0V, V _{CC} WDT is Running | 6,11, g14 |
| | | 5.5V | | 800 | , | 1000 | 600 | μA | V _{IN} = 0V, V _{CC} WDT is Running | 6,11, g14 |
| VICR | Input | 3.0V | 0 | V _{CC} -1.0V | 0 | V _{CC} -1.5V | | V | | 10 |
| | Common Mode Voltage Range | 5.5V | 0 | V _{CC} -1.0V | 0 | V _{CC} -1.5V | | V | | 10 |

| | | v _{cc} | T _A = to +7 | | T _A = - to +1 | | Typical [1] | | | |
|------------------|--------------------------------|-----------------|---------------------------|-----|-----------------------------|-----|-------------|-------|-----------------------------|-------|
| Sym | Parameter | Note [3] | Min | Max | Min | Max | @ 25°C | Units | Conditions | Notes |
| I _{ALL} | Auto Latch | 3.0V | 0.7 | 8 | 0.7 | 10 | 3 | μA | $0V < V_{IN} < V_{CC}$ | 9 |
| | Low Current | 5.5V | 1.4 | 15 | 1.4 | 20 | 5 | μA | $0V < V_{IN} < V_{CC}$ | 9 |
| I _{ALH} | Auto Latch | 3.0V | -0.6 | -5 | -0.6 | -7 | -3 | μA | $0V < V_{IN} < V_{CC}$ | 9 |
| | High Current | 5.5V | -1.0 | -8 | -1.0 | -10 | -6 | μA | $0V < V_{IN} < V_{CC}$ | 9 |
| V _{LV} | V _{CC} Low Voltage | <u>,</u> | | | 2.0 | 3.3 | 2.8 | V | 4 MHz max Int. CLK Freq. | 7,15 |
| | Protection Voltage | | 2.2 | 3.1 | ···· | | 2.8 | | 6 MHz max Int. CLK Freq. | 7,14 |
| V _{OH} | Output High | 3.0V | V _{CC} -0.4 | | V _{CC} -0.4 | | 3.1 | V | I _{OH} = -0.5 mA | |
| | Voltage (Low EMI Mode) | 5.0V | V _{CC} -0.4 | | V _{CC} -0.4 | | 4.8 | V | I _{OH} = -0.5 mA | |
| V _{OL} | Output Low | 3.0V | | 0.6 | | 0.6 | 0.2 | V | l _{OL} = 1.0 mA | |
| | Voltage (Low EMI Mode) | 5.0V | | 0.4 | | 0.4 | 0.1 | V | l _{OL} = 1.0 mA | |

Notes:

1. Typicals are at $V_{CC} = 5.0V$ and 3.3V.

2. GND = 0V.

The V_{DD} voltage specification of 3.0V guarantees 3.3V ±0.3V with typicals at V_{CC}=3.3V, and the V_{DD} voltage specification of 5.5V guarantees 5.0V ±0.5V with typicals at V_{CC}=5.0V.

4. All outputs unloaded, I/O pins floating, inputs at rail.

5. CL1 = CL2 = 10 pF.

6. Same as note [4] except inputs at V_{CC} .

7. The V_{LV} voltage increases as the temperature decreases and will overlap lower V_{CC} operating region.

8. Standard Mode (not Low EMI).

9. Auto Latch (Mask Option) selected.

10. For analog comparator, inputs when analog comparators are enabled.

11. Clock must be forced Low, when XTAL 1 is clock-driven and XTAL2 is floating.

12. Excludes clock pins.

13. Z86C43 only.

14. 0°C to 70°C (standard temperature).

15. -40°C to 150°C (extended temperature).

AC ELECTRICAL CHARACTERISTICS

External I/O or Memory Read and Write Timing Table (C43 Only)

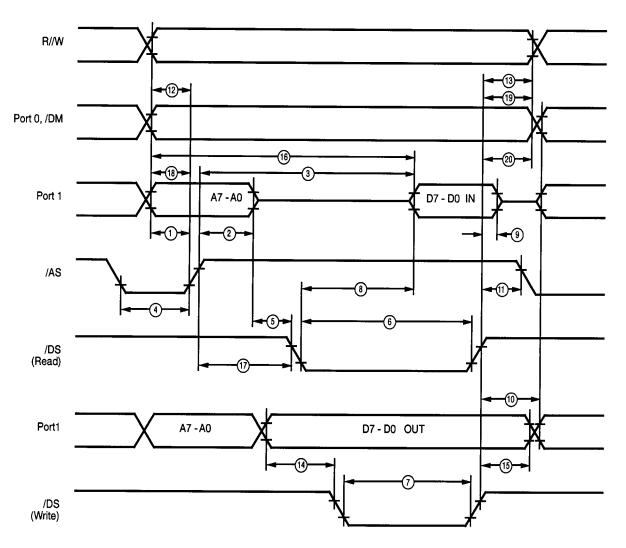


Figure 8. External I/O or Memory Read and Write Timing Table (Z86C43 Only)

AC CHARACTERISTICS

External I/O or Memory Read and Write Timing Table (C43 Only) (SCLK/TCLK = XTAL/2)

| | | | Note | T | A=−0°C | to 70 | °C | T _A = | :40°C | to +1 | 05°C | | |
|----|-----------|-------------------------|-----------------|-----|--------|-------|-----|------------------|-------------|-------|------|----------|-------|
| | | | [3] | 12 | MHz | 16 | MHz | 12 | MHz | 16 | MHz | | |
| No | Symbol | Parameter | V _{CC} | Min | Max | Min | Max | Min | Max | Min | Max | Units | Notes |
| 1 | TdA(AS) | Address Valid to /AS | 3.0 | 35 | | 25 | | 35 | <u></u> | 25 | | ns | 2 |
| | | Rise Delay | 5.5 | 35 | | 25 | | 35 | | 25 | | <u> </u> | 2 |
| 2 | TdAS(A) | /AS Rise to Address | 3.0 | 45 | | 35 | | 45 | | 35 | | ns | 2 |
| | | Float Delay | 5.5 | 45 | | 35 | | 45 | | 35 | | ns | 2 |
| 3 | TdAS(DR) | AS Rise to Read | 3.0 | | 250 | | 180 | | 250 | | 180 | ns | 1,2 |
| | | Data Req'd Valid | 5.5 | | 250 | | 180 | | 250 | | 180 | ns | 2 |
| 4 | TwAS | /AS Low Width | 3.0 | 55 | | 40 | | 55 | ···- | 40 | | ns | 2 |
| | | | 5.5 | 55 | | 40 | | 55 | | 40 | | ns | 2 |
| 5 | TdAS(DS) | Address Float to | 3.0 | 0 | | 0 | | 0 | | 0 | | ns | |
| | | /DS Fall | 5.5 | 0 | | 0 | | 0 | ····· | 0 | | ns | |
| 6 | TwDSR | /DS (Read) Low | 3.0 | 200 | | 135 | | 200 | | 135 | | ns | 1,2 |
| | | Width | 5.5 | 200 | | 135 | | 200 | | 135 | | ns | 1,2 |
| 7 | TwDSW | /DS (Write) Low | 3.0 | 110 | | 80 | | 110 | | 80 | | ns | 1,2 |
| | | Width | 5.5 | 110 | | 80 | | 110 | | 80 | | ns | 1,2 |
| 8 | TdDSR(DR) | /DS Fall to Read Data | 3.0 | | 150 | | 75 | | 150 | | 75 | ns | 1,2 |
| | | Req'd Valid | 5.5 | | 150 | | 75 | | 150 | | 75 | ns | 1,2 |
| 9 | ThDR(DS) | Read Data to /DS Rise | 3.0 | 0 | | 0 | | 0 | | 0 | | ns | 2 |
| | | Hold Time | 5.5 | 0 | | 0 | | 0 | • | 0 | | ns | 2 |
| 10 | TdDS(A) | /DS Rise to Address | 3.0 | 45 | | 50 | | 45 | | 50 | | ns | 2 |
| | | Active Delay | 5.5 | 55 | | 50 | | 55 | | 50 | | ns | 2 |
| 11 | TdDS(AS) | /DS Rise to /AS Fall | 3.0 | 30 | | 35 | | 30 | • **** | 35 | | ns | 2 |
| | | Delay | 5.5 | 45 | | 35 | | 45 | | 55 | | ns | 2 |
| 12 | TdR/W(AS) | R//W Valid to /AS Rise | 3.0 | 45 | | 25 | | 45 | | 25 | | ns | 2 |
| | | Delay | 5.5 | 45 | | 25 | | 45 | | 25 | | ns | 2 |
| 13 | TdDS(R/W) | /DS Rise to R//W | 3.0 | 45 | | 35 | | 45 | | 35 | | ns | 2 |
| | | Not Valid | 5.5 | 45 | | 35 | | 45 | | 35 | | ns | 2 |
| 14 | TdDW(DSW) | Write Data Valid to /DS | 3.0 | 55 | | 25 | | 55 | 4/11 | 25 | | ns | 2 |
| | | Fall (Write) Delay | 5.5 | 55 | | 25 | | 55 | | 25 | | ns | 2 |
| 15 | TdDS(DW) | /DS Rise to Write | 3.0 | 45 | | 35 | | 45 | | 35 | | ns | 2 |
| | | Data Not Valid Delay | 5.5 | 45 | | 35 | | 45 | | 35 | | ns | 2 |
| 16 | TdA(DR) | Address Valid to Read | 3.0 | | 310 | | 230 | | 310 | | 230 | ns | 1,2 |
| | | Data Req'd Valid | 5.5 | | 310 | | 230 | | 310 | | 230 | ns | 1,2 |
| 17 | TdAS(DS) | /AS Rise to /DS | 3.0 | 65 | | 45 | | 65 | | 45 | | ns | 2 |
| | | Fall Delay | 5.5 | 65 | | 45 | | 65 | —— <u>"</u> | 45 | • | ns | 2 |
| 18 | | /DM Valid to /AS | 3.0 | 35 | | 30 | | 35 | | 30 | | ns | 2 |
| | | | 5.5 | 35 | | 30 | | 35 | | 30 | | ns | 2 |

AC CHARACTERISTICS (Continued)

| | | | Note | T | _=−0°C | to 70 | °C | T _A = | :40°C | ; to +1 | 05°C | | |
|----|----------|----------------------|-----------------|-----|--------|-------|-----|------------------|-------|---------|------|-------|-------|
| | | | [3] | 12 | MHz | 16 | MHz | 12 | MHz | 16 | MHz | | |
| No | Symbol | Parameter | V _{CC} | Min | Max | Min | Max | Min | Max | Min | Max | Units | Notes |
| 19 | TdDs(DM) | /DS Rise to DM | 3.0 | 45 | | 35 | | 45 | - | 35 | | ns | 2 |
| - | | Valid Delay | 5.5 | 45 | | 35 | | 45 | | 35 | | ns | 2 |
| 20 | ThDS(AS) | /DS Valid to Address | 3.0 | 45 | | 35 | | 45 | | 35 | | ns | 2 |
| | | Valid Home Time | 5.5 | 45 | | 35 | | 45 | | 35 | | ns | |

Notes:

1. When using extended memory timing add 2 TpC.

2. Timing numbers given are for minimum TpC. 3. The V_{CC} voltage specification of 3.0V guarantees $3.3V \pm 0.3V$, and the V_{DD} voltage specification of 5.5V guarantees $5.0V \pm 0.5V$.

Standard Test Load

All timing references use 0.7 V_{CC} for a logic 1 and 0.2 V_{CC} for a logic 0.

Additional Timing Diagram

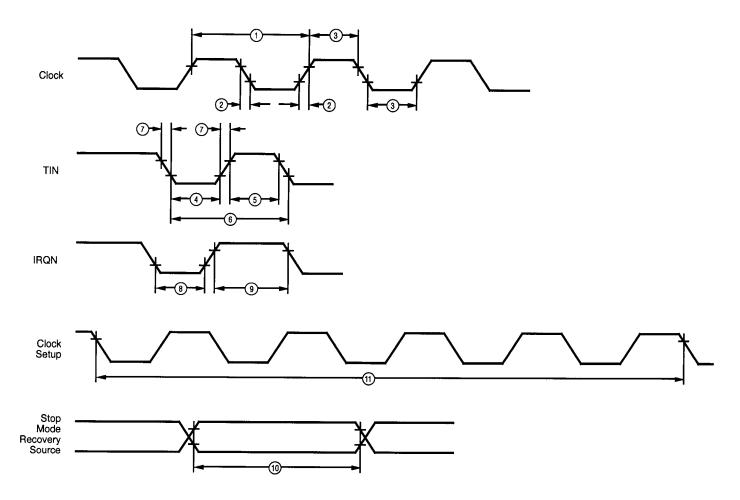


Figure 9. Additional Timing

AC CHARACTERISTICS

Additional Timing Table (SCLK/TCLK = XTAL/2)

| | | | Note | Т | A = 0°C | ; to +70 | °C | T _A | =-4 0°0 | C to +1 | 05°C | | |
|----|---------|----------------------------|-----------------|------|---------|----------|------|----------------|---------|---------|------|-------|------------------|
| | | | [3] | 12 | MHz | 16 | MHz | 12 | MHz | 16 | MHz | | |
| No | Symbol | Parameter | V _{CC} | Min | Max | Min | Max | Min | Max | Min | Max | Units | Notes |
| 1 | ТрС | Input Clock Period | 3.0V | 83 | DC | 62.5 | DC | 83 | DC | 62.5 | DC | ns | 1,7 |
| | | | 5.5V | 83 | DC | 62.5 | DC | 83 | DC | 62.5 | DC | ns | 1,7 |
| | | | 3.0V | 250 | DC | 250 | DC | 250 | DC | 250 | DC | ns | 1,8 |
| | | | 5.5V | 250 | DC | 250 | DC | 250 | DC | 250 | DC | ns | 1,8 |
| 2 | TrC,TfC | Clock Input Rise & | 3.0V | | 15 | | 15 | | 15 | | 15 | ns | 1 |
| | | Fall Times | 5.5V | | 15 | | 15 | | 15 | | 15 | ns | 1 |
| 3 | TwC | Input Clock Width | 3.0V | 41 | | 31 | | 41 | | 31 | | ns | 1 |
| | | | 5.5V | 41 | ** min | 31 | | 41 | | 31 | | ns | 1 |
| | | | 3.0V | 125 | | 125 | | 125 | | 125 | | ns | 1,8 |
| | | | 5.5V | 125 | | 125 | | 125 | | 125 | | ns | 1,8 |
| 4 | TwTinL | Timer Input Low | 3.0V | 100 | | 100 | | 100 | | 100 | | ns | 1 |
| | | Width | 5.5V | 70 | | 70 | | 70 | | 70 | | ns | 1 |
| 5 | TwTinH | Timer Input High | 3.0V | 5TpC | | 5TpC | • | 5TpC | | 5TpC | | | 1 |
| | | Width | 5.5V | 5TpC | | 5TpC | | 5TpC | | 5TpC | | | 1 |
| 6 | TpTin | Timer Input Period | 3.0V | 8TpC | | 8TpC | | 8TpC | | 8TpC | | | 1 |
| | | | 5.5V | 8TpC | | 8TpC | | 8TpC | | 8TpC | | | 1 |
| 7 | TrTin, | Timer Input Rise & | 3.0V | | 100 | | 100 | | 100 | | 100 | ns | 1 |
| | TfTin | Fall Timer | 5.5V | | 100 | | 100 | | 100 | | 100 | ns | 1 |
| 8A | TwIL | Int. Request Low | 3.0V | 100 | | 100 | | 100 | | 100 | | ns | 1,2 |
| | | Time | 5.5V | 70 | | 70 | | 70 | | 70 | | ns | 1,2 |
| 8B | TwiL | Int. Request Low | 3.0V | 5TpC | | 5TpC | | 5TpC | | 5TpC | | | 1,3 |
| | | Time | 5.5V | 5TpC | | 5TpC | | 5TpC | | 5TpC | | | 1,3 |
| 9 | TwlH | Int. Request Input | 3.0V | 5TpC | | 5TpC | | 5TpC | | 5TpC | | | 1,2 |
| | | High Time | 5.5V | 5TpC | | 5TpC | | 5TpC | | 5TpC | | | 1,2 |
| 10 | Twsm | Stop-Mode | 3.0V | 12 | | 12 | | 12 | | 12 | | ns | |
| | | Recovery Width | 5.5V | 12 | - | 12 | | 12 | | 12 | | ns | |
| 11 | Tost | Spec Oscillator Startup | 3.0V | | 5TpC | | 5TpC | | 5TpC | | 5TpC | | 4 |
| | | Time | 5.5V | | 5TpC | | 5TpC | | 5TpC | | 5TpC | | 4 |
| • | | | | | 0100 | | 0100 | | | | orpo | | |
| | | | | | | | | | | | | | D1, D0 [Note] |
| 12 | Twdt | Watch-Dog Timer | 3.0V | 7 | | 7 | | 7 | | 7 | | ms | 0, 0 [5] |
| | | Delay Time | 5.5V | 3.5 | | 3.5 | 4 | 3.5 | | 3.5 | | ms | 0, 0 [5] |
| | | before time-out | 3.0V | 14 | | 14 | | 14 | | 14 | | | 0, 1 [5] |
| | | | 5.5V | 7 | | 7 | | 7 | | 7 | | ms | 0, 1 [5] |
| | | | 3.0V | 28 | | 28 | n.m. | 28 | | 28 | | ms | 1,0[5] |
| | | | 5.5V | 14 | | 14 | | 14 | | 14 | | ms | 1, 0 [5] |
| | | | 3.0V | 112 | | 112 | | 112 | | 112 | | ms | 1, 1 [5] |
| | | | 5.5V | 56 | | 56 | | 56 | | 56 | | ms | 1, 1 [5] |

| | | | Note | T, | $A = 0^{\circ}C$ | to +70 | °C | TA | =-4 0°C | ; to +10 |)5°C | | |
|----|--------|----------------|-----------------|-----|------------------|--------|-----|-----|---------|----------|------|-------------|-------|
| | | | [3] | 12 | MHz | 16 | MHz | 12 | MHz | 16 | MHz | | |
| No | Symbol | Parameter | V _{CC} | Min | Max | Min | Max | Min | Max | Min | Max | Units Notes | Notes |
| 13 | TPOR | Power-On Reset | 3.0V | 3 | 24 | 3 | 24 | 3 | 25 | 3 | 25 | ms | |
| | | Delay | 5.5V | 1.5 | 13 | 1.5 | 13 | 1 | 14 | 1 | 14 | ms | un i |

Notes: :

1. Timing Reference uses 0.7 V_{CC} for a logic 1 and 0.2 V_{CC} for a logic 0.

2. Interrupt request via Port 3 (P31-P33).

3. Interrupt request via Port 3 (P30).

4. SMR-D5 = 0.

5. Reg. WDTMR.

6. The V_{CC} voltage specification of 3.0V guarantees 3.3V ± 0.3V, and the V_{DD} voltage specification of 5.5V guarantees 5.0V ± 0.5V.

7. Standard Oscillator mode, Pcon RegD7=1.

8. Maximum frequency for external XTAL Clock is 4MHz when using low EMI oscillator mode, Pcon Reg D7=0.

AC ELECTRICAL CHARACTERISTICS

Additional Timing Table (Divide-By-One Mode, SCLK/TCLK = XTAL)

| | | | <u> </u> | | 0°C to 0°C | | 40°C to)5°C | | |
|----|--------------|-------------------------|-----------------|------|---------------|-------|-----------------|-------|-------|
| | | | V _{CC} | 8 | MHz | 8 N | <i>l</i> Hz | | |
| No | Symbol | Parameter | Note [6] | Min | Max | Min | Max | Units | Notes |
| 1 | ТрС | Input Clock Period | 3.0V | 250 | DC | 250 | DC | ns | 1,7,8 |
| | | | 5.5V | 250 | DC | 250 | DC | ns | 1,7,8 |
| | | | 3.0V | 125 | DC | 125 | DC | ns | 1,7 |
| | | | 5.5V | 125 | DC | 125 | DC | ns | 1,7 |
| 2 | | Clock Input Rise | 3.0V | | 25 | | 25 | ns | 1,7 |
| | & Fall Times | | 5.5V | | 25 | ····· | 25 | ns | 1,7 |
| 3 | TwC | Input Clock Width | 3.0V | 125 | | 125 | | ns | 1,7,8 |
| | | | 5.5V | 125 | | 125 | | ns | 1,7,8 |
| | | | 3.0V | 62 | | 62 | | ns | 1,7 |
| | | | 5.5V | 62 | | 62 | | ns | 1,7 |
| 4 | TwTinL | Timer Input Low Width | 3.0V | 100 | | 100 | | ns | 1,7 |
| | | | 5.5V | 70 | | 70 | | ns | 1,7 |
| 5 | TwTinH | Timer Input High Width | 3.0V | 3TpC | | 3TpC | | | 1,7 |
| | | | 5.5V | 3TpC | | 3TpC | | | 1,7 |
| 6 | TpTin | Timer Input Period | 3.0V | 4TpC | | 4TpC | | | 1,7 |
| | | | 5.5V | 4TpC | | 4TpC | | | 1,7 |
| 7 | TrTin, | Timer Input Rise | 3.0V | | 100 | | 100 | ns | 1,7 |
| | TfTin | & Fall Timer | 5.5V | | 100 | | 100 | ns | 1,7 |
| 8A | TwIL | Int. Request Low Time | 3.0V | 100 | | 100 | | ns | 1,2,7 |
| | | | 5.5V | 70 | | 70 | | ns | 1,2,7 |
| 8B | TwIL | Int. Request Low Time | 3.0V | 3TpC | | ЗТрС | | | 1,3,7 |
| | | | 5.5V | 3TpC | | ЗТрС | | | 1,3,7 |
| 9 | TwlH | Int. Request Input | 3.0V | 3TpC | | 3TpC | | | 1,2,7 |
| | | High Time | 5.5V | 3TpC | | 2TpC | | | 1,2,7 |
| 10 | Twsm | Stop-Mode Recovery | 3.0V | 12 | | 12 | | ns | 4 |
| | Width Spec | | 5.5V | 12 | | 12 | | ns | 4 |
| 11 | Tost | Oscillator Startup Time | 3.0V | | 5TpC | | 5TpC | | 4,9 |
| | | | 5.5V | | 5TpC | | 5TpC | | 4,9 |

Notes:

1. Timing Reference uses 0.7 V_{CC} for a logic 1 and 0.2 V_{CC} for a logic 0.

2. Interrupt request via Port 3 (P31-P33).

3. Interrupt request via Port 3 (P30).

4. SMR-D5 = 1, POR STOP Mode Delay is on.

5. Reg. WDTMR.

6. The V_{CC} voltage specification of 3.0V guarantees $3.3V \pm 0.3V$, and the V_{DD} voltage specification of 5.5V guarantees $5.0V \pm 0.5V$.

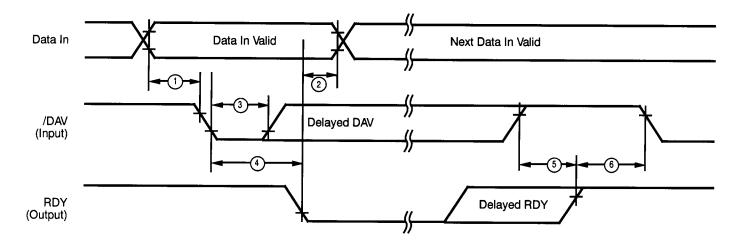
7. SMR D1 = 0.

8. Maximum frequency for external XTAL clock is 4 MHz when using low EMI Oscillator mode Pcon Reg.D7=0.

9. For RC and LC oscillator, and for oscillator driven by clock driver.

18

Handshake Timing Diagrams





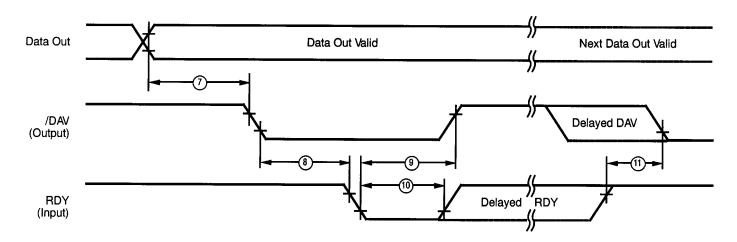


Figure 11. Output Handshake Timing

AC ELECTRICAL CHARACTERISTICS

Handshake Timing Table

| | | | TA | = 0°C | to +7(| D°C | T _A = | -40°C | ; to +1 | 05°C | |
|--------------|---|--|--|--|---|--|---|---|--|---|--|
| | | V _{cc} | 12 | MHz | 16 | MHz | 12 | MHz | 16 | MHz | |
| Symbol | Parameter | Note [1] | Min | Max | Min | Max | Min | Max | Min | Max | Direction Data |
| TsDI(DAV) | Data In Setup Time | 3.0V | 0 | | 0 | | 0 | | 0 | | ÎN |
| | | 5.5V | 0 | | 0 | | 0 | | 0 | | IN |
| ThDI(RDY) | Data In Hold Time | 3.0V | 0 | | 0 | | 0 | | 0 | | IN |
| | | 5.5V | 0 | | 0 | | 0 | | 0 | | IN |
| TwDAV | Data Available Width | 3.0V | 155 | | 155 | | 155 | | 155 | | IN |
| | | 5.5V | 110 | | 110 | | 110 | | 110 | | IN |
| TdDAVI(RDY) | DAV Fall to RDY Fall | 3.0V | | 0 | | 0 | | 0 | | 0 | IN |
| | Delay | 5.5V | | 0 | | 0 | | 0 | | 0 | IN |
| TdDAVId(RDY) | DAV Out to DAV Fall | 3.0V | | 120 | | 120 | | 120 | | 120 | IN |
| | Delay | 5.5V | | 80 | | 80 | | 80 | | 80 | IN |
| RDY0d(DAV) | RDY Rise to DAV Fall | 3.0V | 0 | | 0 | • | 0 | | 0 | | IN |
| | Delay | 5.5V | 0 | | 0 | | 0 | | 0 | | IN |
| TdD0(DAV) | Data Out to DAV Fall | 3.0V | 42 | | 31 | | 42 | | 31 | | OUT |
| | Delay | 5.5V | 42 | | 31 | | 42 | | 31 | | OUT |
| TdDAV0(RDY) | DAV Fall to RDY Fall | 3.0V | 0 | | 0 | | 0 | | 0 | | OUT |
| | Delay | 5.5V | 0 | | 0 | | 0 | | 0 | | OUT |
| TdRDY0(DAV) | RDY Fall to DAV Rise | 3.0V | | 160 | | 160 | | 160 | | 160 | OUT |
| | Delay | 5.5V | | 115 | | 115 | | 115 | | 115 | OUT |
| TwRDY | RDY Width | 3.0V | 110 | | 110 | | 110 | | 110 | | OUT |
| | | 5.5V | 80 | | 80 | | 80 | | 80 | | OUT |
| TdRDY0d(DAV) | RDY Rise to DAV Fall | 3.0V | | 110 | | 110 | | 110 | | 110 | OUT |
| | Delay | 5.5V | | 80 | | 80 | | 80 | | 80 | OUT |
| | TsDI(DAV) ThDI(RDY) TwDAV TdDAVI(RDY) TdDAVId(RDY) TdDAVId(RDY) TdDO(DAV) TdDO(DAV) TdDAV0(RDY) TdRDY0(DAV) TwRDY | TsDI(DAV)Data In Setup TimeThDI(RDY)Data In Hold TimeTwDAVData Available WidthTdDAVI(RDY)DAV Fall to RDY Fall DelayTdDAVId(RDY)DAV Fall to DAV Fall DelayTdDAVId(RDY)DAV Out to DAV Fall DelayRDY0d(DAV)RDY Rise to DAV Fall DelayTdDO(DAV)DAV Fall to RDY Fall DelayTdDAV0(RDY)DAV Fall to RDY Fall DelayTdRDY0(DAV)RDY Fall to RDY Fall DelayTdRDY0(DAV)RDY Fall to DAV Rise DelayTwRDYRDY WidthTdRDY0d(DAV)RDY Rise to DAV Fall | SymbolParameterNote [1]TsDI(DAV)Data In Setup Time3.0V5.5VThDI(RDY)Data In Hold Time3.0VTwDAVData Available Width3.0VTwDAVData Available Width3.0VTdDAVI(RDY)DAV Fall to RDY Fall3.0VDelay5.5VTdDAVId(RDY)DAV Out to DAV Fall3.0VDelay5.5VTdDAVId(RDY)DAV Out to DAV Fall3.0VDelay5.5VTdDO(DAV)RDY Rise to DAV Fall3.0VDelay5.5V3.0VTdDAV0(RDY)DAV Fall to RDY Fall3.0VDelay5.5V5.5VTdDAV0(RDY)DAV Fall to RDY Fall3.0VDelay5.5V5.5VTdRDY0(DAV)RDY Fall to DAV Rise3.0VDelay5.5V5.5VTdRDY0(DAV)RDY Fall to DAV Rise3.0VTdRDY0(DAV)RDY Fall to DAV Fall3.0V5.5VTdRDY0(DAV)RDY Rise to DAV Fall3.0V5.5VTdRDY0(DAV)RDY Rise to DAV Fall3.0V | Symbol Parameter Note [1] Min TsDI(DAV) Data In Setup Time 3.0V 0 5.5V 0 5.5V 0 ThDI(RDY) Data In Hold Time 3.0V 0 TwDAV Data Available Width 3.0V 155 TwDAV Data Available Width 3.0V 155 TdDAVI(RDY) DAV Fall to RDY Fall 3.0V 10 TdDAVI(RDY) DAV Fall to RDY Fall 3.0V 10 Delay 5.5V 110 3.0V 155 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 10 Delay 5.5V 0 10 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 0 Delay 5.5V 0 10 TdDO(DAV) Data Out to DAV Fall 3.0V 42 Delay 5.5V 0 10 TdDAV0(RDY) DAV Fall to RDY Fall 3.0V 0 Delay 5.5V 0 10 TdRDY | Vcc 12 HHz Symbol Parameter Note [1] Min Max TsDI(DAV) Data In Setup Time 3.0V 0 - ThDI(RDY) Data In Hold Time 3.0V 0 - ThDI(RDY) Data In Hold Time 3.0V 0 - TwDAV Data Available Width 3.0V 155 - TdDAVI(RDY) DAV Fall to RDY Fall 3.0V 0 - TdDAVI(RDY) DAV Vout to DAV Fall 3.0V 0 - Delay 5.5V 0 - - - TdDAVId(RDY) DAV Out to DAV Fall 3.0V 0 - - Delay 5.5V 0 - - - - TdDAVId(RDY) DAV Out to DAV Fall 3.0V 42 - - Delay 5.5V 0 - - - - TdDAVO(RDY) DAV Fall to RDY Fall 3.0V 42 - - Delay <td>Vcc 12 HHz 16 Symbol Parameter Note [1] Min Max Min TsDI(DAV) Data In Setup Time 3.0V 0 0 TsDI(DAV) Data In Setup Time 3.0V 0 0 ThDI(RDY) Data In Hold Time 3.0V 0 0 TwDAV Data Available Width 3.0V 155 155 TdDAV Data Available Width 3.0V 0 0 TdDAVI(RDY) DAV Fall to RDY Fall 3.0V 0 0 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 120 110 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 120 0 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 120 0 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 0 0 TdDAVId(RDY) DAV Fall to RDY Fall 3.0V 42 31 Delay 5.5V 42 31 0 0 TdDAVO(RDY) DAV Fall to R</td> <td>Symbol Parameter Note [1] Min Max TsDI(DAV) Data In Setup Time 3.0V 0 0 ThDI(RDY) Data In Hold Time 3.0V 0 0 TwDAV Data Available Width 3.0V 0 0 TwDAV Data Available Width 3.0V 155 155 TdDAVI(RDY) DAV Fall to RDY Fall 3.0V 0 0 TdDAVI(RDY) DAV Fall to RDY Fall 3.0V 0 0 TdDAVI(RDY) DAV Fall to DAV Fall 3.0V 0 0 TdDAVI(RDY) DAV Out to DAV Fall 3.0V 0 0 Delay 5.5V 0 0 120 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 0 0 Delay 5.5V 0 0 0 120 TdDO(DAV) Data Out to DAV Fall 3.0V 42 31 15 Delay 5.5V 0 0 0 160 160</td> <td>Vcc 12 Hz 16 Hz 12 Hz Symbol Parameter Note [1] Min Max Min Max</td> <td>Vcc 12 Hz 16 Hz 12 Hz Symbol Parameter Note [1] Min Max Min Max Min Max TsDI(DAV) Data In Setup Time 3.0V 0 0 0 0 TsDI(DAV) Data In Setup Time 3.0V 0 0 0 0 ThDI(RDY) Data In Hold Time 3.0V 0 0 0 0 TwDAV Data Available Width 3.0V 155 155 155 TdDAVI(RDY) DAV Fall to RDY Fall 3.0V 0 0 0 TdDAVI(RDY) DAV fall to RDY Fall 3.0V 120 120 120 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 120 120 120 Delay 5.5V 80 80 80 80 80 RDYOd(DAV) RDY Rise to DAV Fall 3.0V 0 0 0 120 Delay 5.5V 0 0 0 0 120</td> <td>Vcc 12 Hz 16 Hz 12 Hz 16 I Symbol Parameter Note [1] Min Max Min Max<</td> <td>Vcc 12 Hz 16 Hz 12 Hz 16 16 16 16 16</td> | Vcc 12 HHz 16 Symbol Parameter Note [1] Min Max Min TsDI(DAV) Data In Setup Time 3.0V 0 0 TsDI(DAV) Data In Setup Time 3.0V 0 0 ThDI(RDY) Data In Hold Time 3.0V 0 0 TwDAV Data Available Width 3.0V 155 155 TdDAV Data Available Width 3.0V 0 0 TdDAVI(RDY) DAV Fall to RDY Fall 3.0V 0 0 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 120 110 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 120 0 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 120 0 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 0 0 TdDAVId(RDY) DAV Fall to RDY Fall 3.0V 42 31 Delay 5.5V 42 31 0 0 TdDAVO(RDY) DAV Fall to R | Symbol Parameter Note [1] Min Max TsDI(DAV) Data In Setup Time 3.0V 0 0 ThDI(RDY) Data In Hold Time 3.0V 0 0 TwDAV Data Available Width 3.0V 0 0 TwDAV Data Available Width 3.0V 155 155 TdDAVI(RDY) DAV Fall to RDY Fall 3.0V 0 0 TdDAVI(RDY) DAV Fall to RDY Fall 3.0V 0 0 TdDAVI(RDY) DAV Fall to DAV Fall 3.0V 0 0 TdDAVI(RDY) DAV Out to DAV Fall 3.0V 0 0 Delay 5.5V 0 0 120 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 0 0 Delay 5.5V 0 0 0 120 TdDO(DAV) Data Out to DAV Fall 3.0V 42 31 15 Delay 5.5V 0 0 0 160 160 | Vcc 12 Hz 16 Hz 12 Hz Symbol Parameter Note [1] Min Max Min Max | Vcc 12 Hz 16 Hz 12 Hz Symbol Parameter Note [1] Min Max Min Max Min Max TsDI(DAV) Data In Setup Time 3.0V 0 0 0 0 TsDI(DAV) Data In Setup Time 3.0V 0 0 0 0 ThDI(RDY) Data In Hold Time 3.0V 0 0 0 0 TwDAV Data Available Width 3.0V 155 155 155 TdDAVI(RDY) DAV Fall to RDY Fall 3.0V 0 0 0 TdDAVI(RDY) DAV fall to RDY Fall 3.0V 120 120 120 TdDAVId(RDY) DAV Out to DAV Fall 3.0V 120 120 120 Delay 5.5V 80 80 80 80 80 RDYOd(DAV) RDY Rise to DAV Fall 3.0V 0 0 0 120 Delay 5.5V 0 0 0 0 120 | Vcc 12 Hz 16 Hz 12 Hz 16 I Symbol Parameter Note [1] Min Max Min Max< | Vcc 12 Hz 16 Hz 12 Hz 16 16 16 16 16 |

Notes:

1. Timing Reference uses 0.7 V_{CC} for a logic 1 and 0.2 V_{CC} for a logic 0.

2. The V_{CC} voltage specification of 3.0V guarantees 3.3V ± 0.3V and the V_{DD} voltage specification of 5.5V guarantees 5.0V ± 0.5V.

ROM Mask options available:

- 1. Enable ROM Protect
- 2. Enable RAM Protect
- 3. RC or Crystal Clock Source
- 4. WDT automatically enabled after reset.
- 5. Enable autolatches

PIN FUNCTIONS

/ROMIess (input, active Low). This pin, when connected to GND, disables the internal ROM and forces the device to function as a Z86C90 ROMIess Z8. (Note that, when left unconnected or pulled High to V_{CC} , the device functions normally as a Z8 ROM version) Not available on Z86C33.

Note: When using in ROM Mode in High EMI (noisy) environment, the ROMless pins should be connected directly to $V_{CC}.$

/DS (output, active Low). Data Strobe is activated once for each external memory transfer. For a READ operation, data must be available prior to the trailing edge of /DS. For WRITE operations, the falling edge of /DS indicates that output data is valid. Not available on Z86C33.

/AS (output, active Low). Address Strobe is pulsed once at the beginning of each machine cycle for external memory transfer. Address output is from Port 0/Port 1 for all external programs. Memory address transfers are valid at the trailing edge of /AS. Under program control, /AS is placed in the high-impedance state along with Ports 0 and 1, Data Strobe, and Read/Write. Not available on Z86C33.

XTAL1 Crystal 1 (time-based input). This pin connects a parallel-resonant crystal, ceramic resonator, LC, or RC network, or an external single-phase clock to the on-chip oscillator input.

XTAL2 Crystal 2 (time-based output). This pin connects a parallel-resonant crystal, ceramic resonant, LC, or RC network to the on-chip oscillator output.

R//**W** (output, write Low). Read/Write, the R//W signal is Low when the Z86C33/43 is writing to the external program or data memory. Not available on Z86C33.

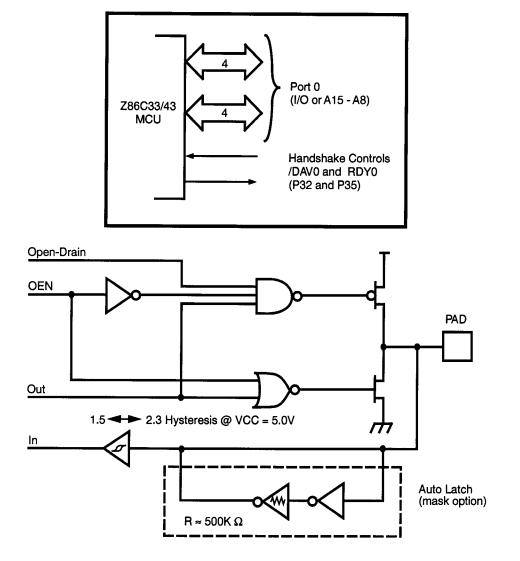
Port 0 (P00-P07). Port 0 is an 8-bit, bidirectional, CMOScompatible port. These eight I/O lines are configured under software control as a nibble I/O port (P03-P00 input/output and P07-P04 input/output), or as an address port for interfacing external memory. The input buffers are Schmitt-triggered and nibble-programmed as outputs and can be globally programmed as either push-pull or opendrain. Low EMI output buffers can be globally programmed by the software. Port 0 is placed under handshake control. In this configuration, Port 3, lines P32 and P35 are used as the handshake control /DAV0 and RDY0. Handshake signal direction is dictated by the I/O direction (input or output) of Port 0 of the upper nibble P04-P07. The lower nibble must have the same direction as the upper nibble.

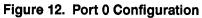
For external memory references, Port 0 provides address bits A11-A8 (lower nibble) or A15-A8 (lower and upper nibble) depending on the required address space. If the address range requires 12 bits or less, the upper nibble of Port 0 can be programmed independently as I/O while the lower nibble is used for addressing. If one or both nibbles are needed for I/O operation, they are configured by writing to the Port 0 mode register.

In ROMless mode, after a hardware reset, Port 0 is configured as address lines A15-A8, and extended timing is set to accommodate slow memory access. The initialization routine can include reconfiguration to eliminate this extended timing mode. (In ROM mode, Port 0 is defined as input after reset.)

Port 0 is set in the High-Impedance Mode if selected as an address output state along with Port 1 and the control signals /AS, /DS, and R//W (Figure 12).

PIN FUNCTIONS (Continued)





Port 1 (P17-P10). Port 1 is an 8-bit, bidirectional, CMOScompatible port (Figure 13), with multiplexed Address (A7-A0) and Data (D7-D0) ports. For the Z86C33/43 ROM device, these eight I/O lines are programmed as inputs or outputs, or can be configured under software control as an Address/Data port for interfacing external memory. The input buffers are Schmitt-triggered and byte-programmed as outputs and can be globally programmed as either pushpull or open-drain. Low EMI output buffers can be globally programmed by the software. Note: Port 1 is not available on Z86C33 and P01M Register for Z86C33 must have Bit D4,D3 set as 00.

Note: Low EMI mode is not supported on the emulator for Port1. Pcon reg. D4 must be 1.

Port 1 may be placed under handshake control. In this configuration, Port 3, lines P33 and P34 are used as the handshake controls RDY1 and /DAV1 (Ready and Data Available). Memory locations greater than 4095 are referenced through Port 1. To interface external memory, Port 1 must be programmed for the multiplexed Address/Data mode. If more than 256 external locations are required, Port 0 outputs the additional lines.

Port 1 can be placed in the high-impedance state along with Port 0, /AS, /DS, and R//W, allowing the Z86C33/43 to share common resources in multiprocessor and DMA applications.

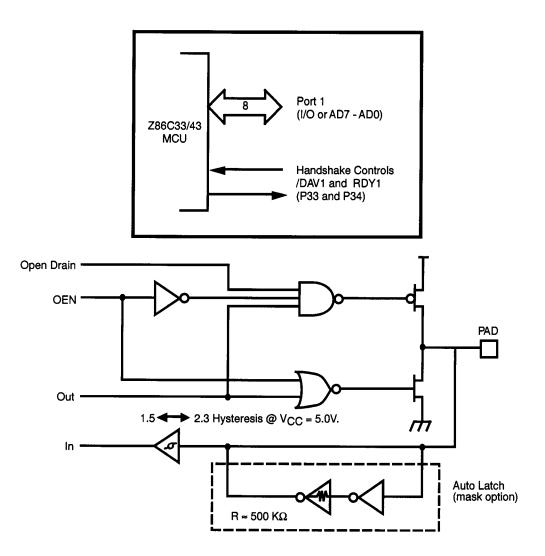


Figure 13. Port 1 Configuration

PIN FUNCTIONS (Continued)

Port 2 (P27-P20). Port 2 is an 8-bit, bidirectional, CMOScompatible I/O port. These eight I/O lines are configured under software control as an input or output, independently. Port 2 is always available for I/O operation. The input buffers are Schmitt-triggered. Bits programmed as outputs may be globally programmed as either push-pull or opendrain. Low EMI output buffers can be globally programmed by the software. Port 2 may be placed under handshake control. In this Handshake Mode, Port 3 lines P31 and P36 are used as the handshake controls lines /DAV2 and RDY2. The handshake signal assignment for Port 3 lines P31 and P36 is dictated by the direction (input or output) assigned to bit 7, Port 2 (Figure 14).

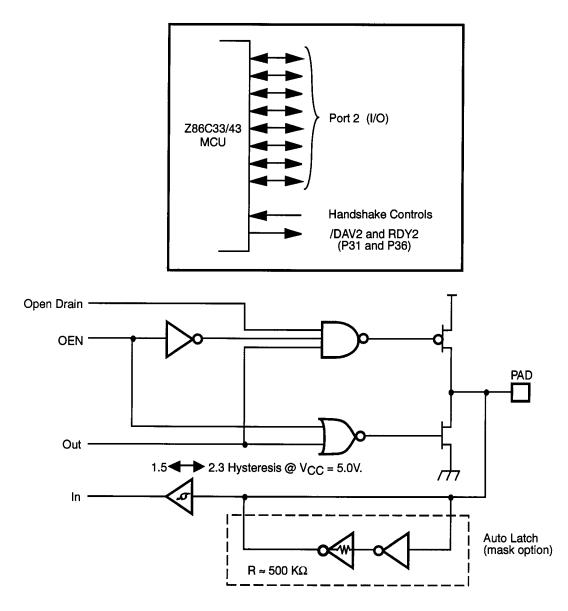


Figure 14. Port 2 Configuration

Port 3 (P37-P30). Port 3 is an 8-bit, CMOS-compatible, four fixed inputs (P33-P30) and four fixed outputs (P34-P37), and is configured under software control for Input/Output, Counter/Timers, interrupt, port handshake, and Data Memory functions. Port 3, pin 0 input is Schmitttriggered, and pins P31, P32, and P33 are standard CMOS inputs (no Auto Latches). Pins P34, P35, P36, P37 are push-pull output lines. Low EMI output buffers can be globally programmed by the software.

Two on-board comparators can process analog signals on P31 and P32 with reference to the voltage on P33. The analog function is enabled by programming Port 3 Mode Register (P3M bit 1). For Interrupt functions. Port 3, pin 0 and pin 3 are falling edge interrupt inputs. P31 and P32 are programmable as rising, falling, or both edge triggered interrupts (IRQ register bits 6 and bit 7). P33 is the comparator reference voltage input when in Analog Mode. Access

to Counter/Timers 1 is made through P31 (TIN) and P36 (TOUT). Handshake lines for Ports 0, 1, and 2 are available on P31 through P36.

Port 3 also provides the following control functions: handshake for Ports 0, 1, and 2 (/DAV and RDY); four external interrupt request signals (IRQ3-IRQ0); timer input and output signals (TIN and TOUT); Data Memory Select (/DM, see Table 5, Figure 43).

P34 output can be software-programmed to function as a Data Memory Select (DM). The Port 3 mode register (P3M) bit D3, D4 selects this function. When accessing external Data Memory, the P34 goes active Low: when accessing external program memory, the P34 goes High.

| Pin | I/O | CTC1 | Analog | Int. | P0 HS | P1 HS | P2 HS | Ext |
|-----|---------------------------------------|-----------------|--|------|---------------------------------------|-------|-------|-----|
| P30 | IN | | ······································ | IRQ3 | | | | |
| P31 | IN | T _{IN} | AN1 | IRQ2 | | | D/R | |
| P32 | IN | | AN2 | IRQ0 | D/R | | | |
| P33 | IN | | REF | IRQ1 | · · · · · · · · · · · · · · · · · · · | D/R | | |
| P34 | OUT | | AN1-OUT | | | R/D | ···· | /DN |
| P35 | OUT | ····· | ,,- <u></u> | | R/D | | | · |
| P36 | OUT | TOUT | | | | | R/D | |
| P37 | OUT | | AN2-OUT | | | | | · |
| es: | · · · · · · · · · · · · · · · · · · · | • • •• •• | | | | | | |

Table 5. Port 3 Pin Assignments

Auto Latch. The Auto Latch instruction puts valid CMOS levels on all CMOS inputs (except P33-P31) that are not externally driven. Whether this level is 0 or 1, cannot be determined. A valid CMOS level, rather than a floating node, reduces excessive supply current flow in the input buffer.

Note: Deletion of all Port Auto Latches is available as a ROM Mask option. The Auto Latch Delete option is selected by the customer when the ROM code is submitted.

Comparator Inputs. Port 3, Pins P31 and P32 each have a comparator front end. The comparator reference voltage, pin P33, is common to both comparators. In analog mode, the P31 and P32 are the positive inputs to the comparators and P33 is the reference voltage supplied to both comparators. In digital mode, pin P33 can be used as a P33 register input or IRQ1 source. P34 and P37 outputs the comparator outputs by software-programming the PCON Reg. bit D0 to 1.

Note: Must add a two NOP delay after selecting the P3M bit D1 to 1 before the comparitor output is valid. IRQ0, IRQ1, and IRQ2 should be cleared in IRQ register when the comparitor is enabled or disabled to avoid spurious noise creating a false interrupt.

HS = Handshake Signals

D = /DAV

R = RDY

PIN FUNCTIONS (Continued)

/RESET (input, active Low). Initializes the MCU. Reset is accomplished either through Power-On Reset, Watch-Dog Timer reset, STOP-Mode Recovery, or external reset. During Power-On Reset and Watch-Dog Reset, the internally generated reset is driving the reset pin Low for the POR time. Any devices driving the reset line must be opendrain to avoid damage from a possible conflict during reset conditions. RESET does depend on oscillator operating to achieve full reset conditions except a permanently enabled WDT reset. Pull-up is provided internally.

Note: /RESET pin is not available on Z86C33.

After the POR time, /RESET is a Schmitt-triggered input. During the reset cycle, /DS is held active Low while /AS cycles at a rate of TpC/2. Program execution begins at location 000C (HEX), after the RST is released. For Power-On Reset, the reset output time is TPOR ms.

Once program execution begins, /AS and /DS toggles only for external memory accesses. The Z86C33/43 does not reset WDTMR, SMR, P2M, PCON, and P3M registers on a Stop-Mode Recovery operation or from a WDT reset out of STOP Mode.

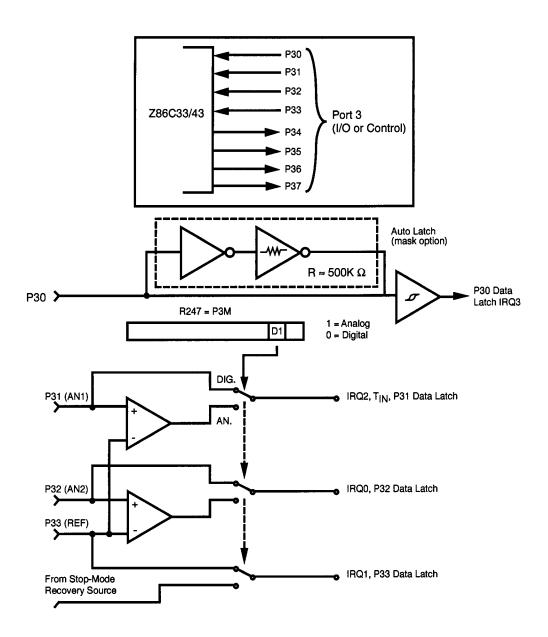
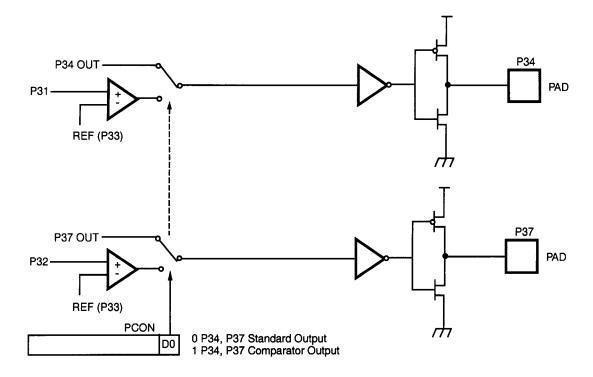
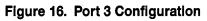


Figure 15. Port 3 Configuration





FUNCTIONAL DESCRIPTION

The Z86C33/43 MCU incorporates the following special functions to enhance the standard Z8® architecture to provide the user with increased design flexibility.

RESET. The device is reset in one of the following conditions:

- Power-On Reset
- Watch-Dog Timer
- Stop-Mode Recovery Source
- External Reset
- Low Voltage Recovery

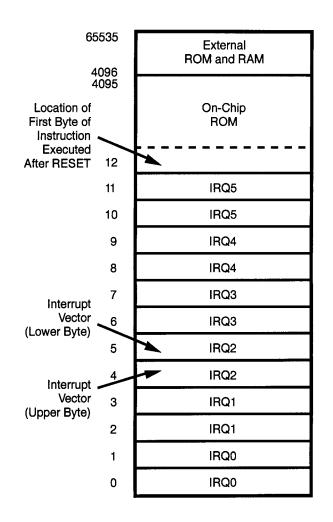
Auto Power-On Reset circuitry is built into the Z86C33/43, eliminating the need for an external reset circuit to reset upon power-up. The internal pull-up resistor is on the Reset pin, so a pull-up resistor is not required; however, in high EMI (noisy) environment, it is recommended that a small value pull-up resistor be used.

Note: /RESET pin is not available on Z86C33.

Program Memory. The Z86C33/43 addresses up to 4 KB of internal program memory and 60 KB of external memory (Figure 18). The first 12 bytes of program memory are reserved for the interrupt vectors. These locations contain six 16-bit vectors that correspond to the six available interrupts. For ROM mode, address 12 to address 4095 consists of on-chip mask-programmed ROM. At addresses 4096 and greater, the Z86C33/43 executes external program memory fetches through Port 0 and Port 1 in Address/Data mode.

The 4 KB program memory is mask programmable. A ROM protect feature prevents "dumping" of the ROM contents by inhibiting execution of LDC, LDCI, LDE, and LDEI instructions to Program Memory in external program mode. ROM look-up tables can be used with this feature.

The ROM Protect option is mask-programmable, to be selected by the customer when the ROM code is submitted.





FUNCTIONAL DESCRIPTION (Continued)

Data Memory (/DM). The Z86C33/43 ROM version can address up to 60 KB of external data memory beginning at location 4096. External data memory may be included with, or separated from, the external program memory space. /DM, an optional I/O function that can be programmed to appear on pin P34, is used to distinguish between data and program memory space (Figure 19). The state of the /DM signal is controlled by the type of instruction being executed. An LDC opcode references PRO-GRAM (/DM inactive) memory, and an LDE instruction references data (/DM active Low) memory. The user must configure Port 3 Mode Register (P3M) bits D3 and D4 for this mode. Available only on Z86C43.

Expanded Register File (ERF). The Z86C33/43 register file has been expanded to allow for additional system control registers, and for mapping of additional peripheral devices along with I/O ports into the register address area. The Z8 register address space R0 through R15 has now been implemented as 16 groups of 16 registers per group (Figure 18). These register groups are known as the Expanded Register File (ERF). Bits 7-4 of register RP select the working register group. Bits 3-0 of register RP select the expanded register group (Figure 18). Three system configuration registers reside in the Expanded Register File at Bank F (PCON, SMR, WDTMR). The rest of the Expanded Register is not physically implemented, and is open for future expansion.

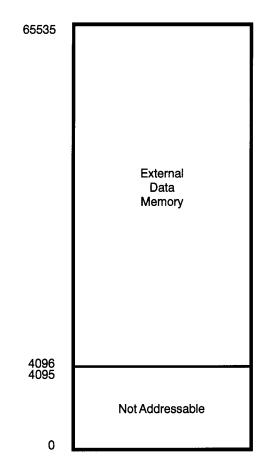


Figure 18. Data Memory Map

Z8® STANDARD CONTROL REGISTERS

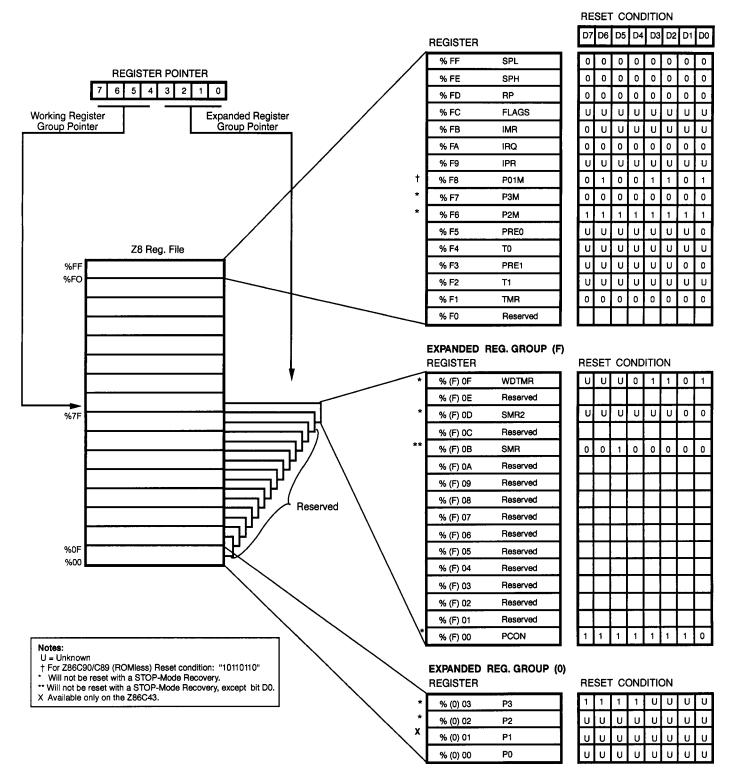
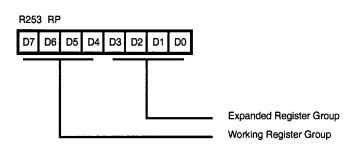


Figure 19. Expanded Register File Architecture

Register File. The register file consists of four I/O port registers, 236 general-purpose registers and 15 control and status registers (R0-R3, R4-239 and R240-R255, respectively), plus three system configuration registers in the expanded register group. The instructions access registers directly or indirectly through an 8-bit address field. This allows a short, 4-bit register address using the Register Pointer (Figure 22). In the 4-bit mode, the register file is divided into 16 working register groups, each occupying 16 continuous locations. The Register Pointer addresses the starting location of the active working register group.



Default setting after RESET = 00000000



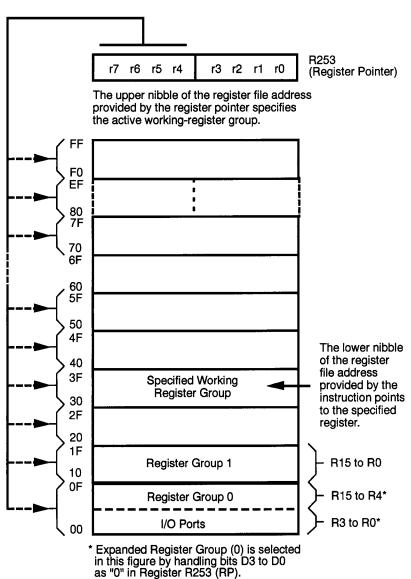


Figure 21. Register Pointer

General-Purpose Registers (GPR). These registers are undefined after the device is powered up. The registers keep their last value after any reset, as long as the reset occurs in the V_{CC} voltage-specified operating range. It will not keep its last state from a V_{LV} reset if the V_{CC} drops below 1.8V.

Note: Register Bank E0-EF is only accessed through working register and indirect addressing modes.

RAM Protect. The upper portion of the RAM's address spaces %80F to %EF (excluding the control registers) are protected from writing. The RAM Protect bit option is mask-programmable and is selected by the customer when the ROM code is submitted. After the mask option is selected, the user activates this feature from the internal ROM code to turn off/on the RAM Protect by loading either a 0 or 1 into the IMR register, bit D6. A 1 in D6 enables RAM Protect.

Stack. The Z86C33/43 external data memory or the internal register file is used for the stack. The 16-bit Stack Pointer (R254-R255) is used for the external stack, which can reside anywhere in the data memory for ROMless mode, but only from 4096 to 65535 in ROM mode. An 8-bit Stack Pointer (R255) is used for the internal stack that resides within the 236 general-purpose registers (R4-R239). SPH is used as a general-purpose register when using internal stack only. The Z86C33 uses the 8-bit stack pointer (R255) for internal stack only.

Note: R254 and R255 are set to 00Hex after any reset or Stop-Mode Recovery.

Counter/Timers. There are two 8-bit programmable counter/timers (T0-T1), each driven by its own 6-bit programmable prescaler. The T1 prescaler is driven by internal or external clock sources; however, the T0 prescaler is driven by the internal clock only (Figure 23).

The 6-bit prescalers can divide the input frequency of the clock source by any integer number from 1 to 64. Each prescaler drives its counter, which decrements the value (1 to 256) that has been loaded into the counter. When the counter reaches the end of the count, a timer interrupt request, IRQ4 (T0) or IRQ5 (T1), is generated.

The counters can be programmed to start, stop, restart to continue, or restart from the initial value. The counters can also be programmed to stop upon reaching zero (single pass mode) or to automatically reload the initial value and continue counting (modulo-n continuous mode).

The counters, **but not the prescalers**, are read at any time without disturbing their value or count mode. The clock source for T1 is user-definable and is either the internal microprocessor clock divide-by-four, or an external signal input through Port 3. The Timer Mode register configures the external timer input (P31) as an external clock, a trigger input that can be retriggerable or non-retriggerable, or as a gate input for the internal clock. The counter/timers can be cascaded by connecting the T0 output to the input of T1. TIN Mode is enabled by setting R243 PRE1 Bit D1 to 0.

FUNCTIONAL DESCRIPTION (Continued)

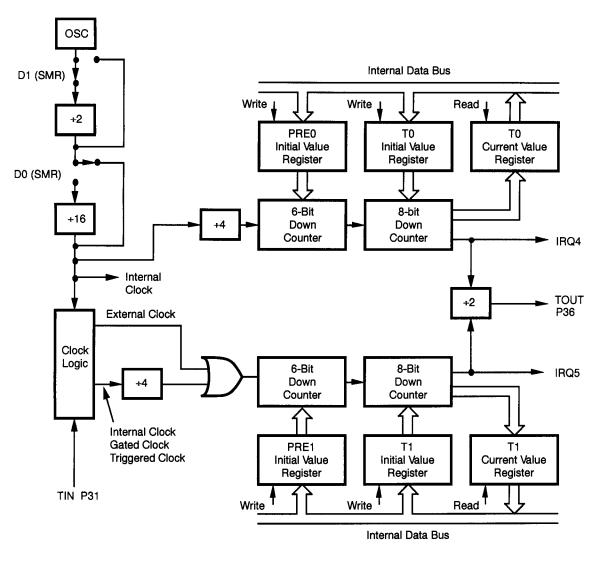


Figure 22. Counter/Timer Block Diagram

Interrupts. The Z86C33/43 has six different interrupts from six different sources. These interrupts are maskable, prioritized (Figure 23) and the six sources are divided as follows: four sources are claimed by Port 3 lines P33-P30, and two in counter/timers (Table 6). The Interrupt Mask

Register globally or individually enables or disables the six interrupt requests.

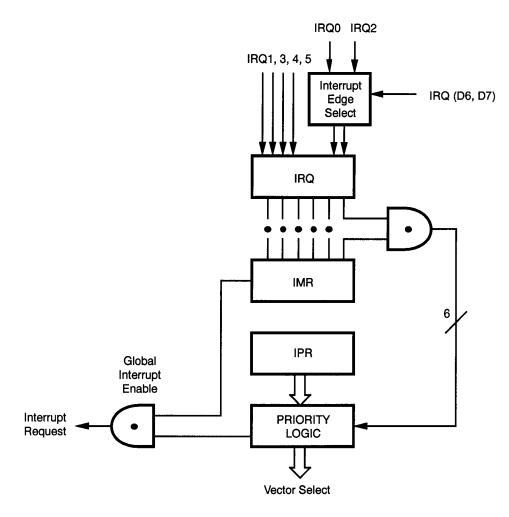




Table 6. Interrupt Types, Sources, and Vectors

| Name | Source | Vector Location | Comments |
|-------|------------------|--------------------|--|
| IRQ0 | /DAV0, IRQ0 | 0, 1 | External (P32), Rise Fall Edge Triggered |
| IRQ1, | IRQ1 | 2, 3 | External (P33), Fall Edge Triggered |
| IRQ2 | /DAV2, IRQ2, TIN | 4, 5 | External (P31), Rise Fall Edge Triggered |
| IRQ3 | IRQ3 | 6, 7 | External (P30), Fall Edge Triggered |
| IRQ4 | TO | 8, 9 | Internal |
| IRQ5 | T1 | 10, 11 | Internal |

FUNCTIONAL DESCRIPTION (Continued)

When more than one interrupt is pending, priorities are resolved by a programmable priority encoder that is controlled by the Interrupt Priority register. An interrupt machine cycle is activated when an interrupt request is granted. This action disables all subsequent interrupts, saves the Program Counter and Status Flags, and then branches to the program memory vector location reserved for that interrupt.

All Z86C33/43 interrupts are vectored through locations in the program memory. This memory location and the next byte contain the 16-bit address of the interrupt service routine for that particular interrupt request. To accommodate polled interrupt systems, interrupt inputs are masked and the Interrupt Request register is polled to determine which of the interrupt requests need service.

An interrupt resulting from AN1 is mapped into IRQ2, and an interrupt from AN2 is mapped into IRQ0. Interrupts IRQ2 and IRQ0 may be rising, falling, or both edge triggered, and are programmable by the user. The software may poll to identify the state of the pin. When in analog mode, the IRQ1 is generated by the Stop-Mode Recovery source selected by SMR Reg. bits D4,D3,D2, or SMR2 D1or D0.

Programming bits for the Interrupt Edge Select is located in the IRQ Register (R250), bits D7 and D6. The configuration is shown in Table 7.

| IF | Q | Interrupt Edge | | | | |
|----|--------|----------------|-----|--|--|--|
| D7 | D6 | P31 | P32 | | | |
| 0 | 0 | F | F | | | |
| 0 | 1 | F | R | | | |
| 1 | 0 | R | F | | | |
| 1 | 1 | R/F | R/F | | | |
| s: | ·····* | | | | | |

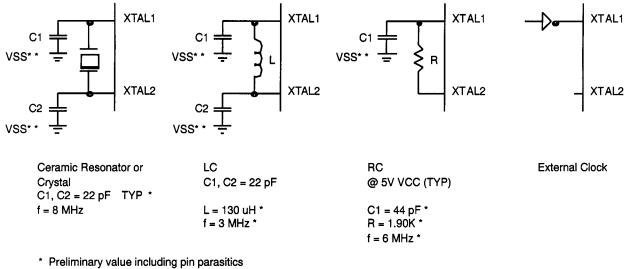
Table 7. IRQ Register

Note

F = Falling EdgeR = Rising Edge **Clock.** The Z86C33/43 on-chip oscillator has a high-gain, parallel-resonant amplifier for connection to a crystal, LC, RC, ceramic resonator, or any suitable external clock source (XTAL1 = Input, XTAL2 = Output). The crystal should be AT cut, 16 MHz max., with a series resistance (RS) of less than or equal to 100 Ohms when counting from 1 MHz to 16 MHz.

The crystal should be connected across XTAL1 and XTAL2 using the vendor's recommended capacitor values from each pin directly to the device Ground pin to reduce Ground noise injection into the oscillator. The RC oscillator option is mask-programmable on the Z86C33/43 and is selected by the customer at the time when the ROM code is submitted. (Note that the RC option is available up to 8 MHz.) The RC oscillator configuration must be an external resistor connected from XTAL1 to XTAL2, with a frequency-setting capacitor from XTAL1 to Ground (Figure 24).

Note: For better noise immunity, the capacitors should be tied directly to the device Ground pin (V_{SS}).



* Device ground pin

Figure 24. Oscillator Configuration

Power-On-Reset (POR). A timer circuit clocked by a dedicated on-board RC oscillator is used for the Power-On Reset (POR) timer function. The POR time allows V_{CC} and the oscillator circuit to stabilize before instruction execution begins.

The POR timer circuit is a one-shot timer triggered by one of three conditions:

- 1. Power fail to Power OK status.
- 2. Stop-Mode Recovery (if D5 of SMR=1).
- 3. WDT time-out.

The POR time is a specified as TPOR. Bit 5 of the STOP-Mode Register determines whether the POR timer is bypassed after Stop-Mode Recovery (typical for external clock, RC/LC oscillators).

HALT. HALT turns off the internal CPU clock, but not the XTAL oscillation. The counter/timers and external interrupts IRQ0, IRQ1, IRQ2, and IRQ3 remain active. The devices are recovered by interrupts, either externally or internally generated. An interrupt request must be enabled and executed to exit HALT Mode. After the interrupt service routine, the program continues from the instruction after the HALT.

In order to enter STOP (or HALT) Mode, it is necessary to first flush the instruction pipeline to avoid suspending execution in mid-instruction. To do this, the user must execute

a NOP (opcode=FFH) immediately before the appropriate sleep instruction, i.e.:

| FF | NOP | ; clear the pipeline |
|----|------|----------------------|
| 6F | STOP | ; enter STOP Mode |
| | | or |
| FF | NOP | ; clear the pipeline |
| 7F | HALT | ; enter HALT Mode |

STOP. This instruction turns off the internal clock and external crystal oscillation. It also reduces the standby current to 10 μ A or less. The STOP Mode is terminated by a reset only, either by WDT time-out, POR, SMR recovery, or external reset. This causes the processor to restart the application program at address 000C (HEX).A WDT time out in STOP Mode will affect all registers the same as if a Stop-Mode Recovery occurred via a selected Stop-Mode Recovery source except that the POR delay is enabled even if the delay is selected for disable.

Note: If permanent WDT is selected, the WDT will run in all modes and can not be stopped or disabled if on board RC oscillator is selected to drive the WDT.

Port Configuration Register (PCON). The PCON register configures the ports individually; comparator output on Port 3, open-drain on Port 0 and Port 1, low EMI on Ports 0, 1, 2, and 3, and low EMI oscillator. The PCON register is located in the expanded register file at Bank F, location 00 (Figure 25).

FUNCTIONAL DESCRIPTION (Continued)

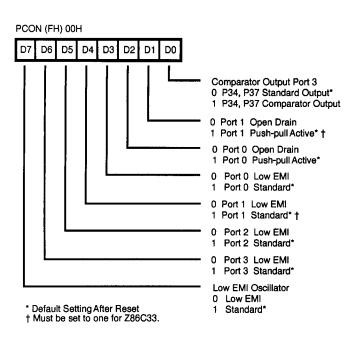


Figure 25. Port Configuration Register (PCON) (Write Only)

Comparator Output Port 3 (D0). Bit 0 controls the comparator use in Port 3. A 1 in this location brings the comparator outputs to P34 and P37, and a 0 releases the Port to its standard I/O configuration. The default value is 0.

Port 1 Open-Drain (D1). Port 1 can be configured as an open-drain by resetting this bit (D1=0) or configured as push-pull active by setting this bit (D1=1). The default value is 1. Must set D1=1 for Z86C33.

Port 0 Open-Drain (D2). Port 0 can be configured as an open-drain by resetting this bit (D2=0) or configured as push-pull active by setting this bit (D2=1). The default value is 1.

Low EMI Port 0 (D3). Port 0 can be configured as a Low EMI Port by resetting this bit (D3=0) or configured as a Standard Port by setting this bit (D3=1). The default value is 1.

Low EMI Port 1 (D4). Port 1 can be configured as a Low EMI Port by resetting this bit (D4=0) or configured as a Standard Port by setting this bit (D4=1). The default value is 1. Must be set D4=1 for Z86C33.

Note: For emulator, this bit must be set to 1.

Low EMI Port 2 (D5). Port 2 can be configured as a Low EMI Port by resetting this bit (D5=0) or configured as a Standard Port by setting this bit (D5=1). The default value is 1.

Low EMI Port 3 (D6). Port 3 can be configured as a Low EMI Port by resetting this bit (D6=0) or configured as a Standard Port by setting this bit (D6=1). The default value is 1.

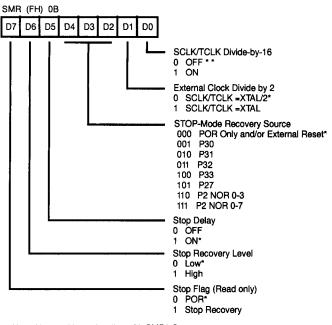
Low EMI OSC (D7). This bit of the PCON Register controls the low EMI noise oscillator. A 1 in this location configures the oscillator, /DS, /AS and R//W with standard drive, while a 0 configures the oscillator, /DS, /AS and R//W with low noise drive. The low EMI mode will reduce the drive of the oscillator (OSC). The default value is 1. Note: Maximum external clock frequency of 4 MHz when running in the low EMI oscillator mode.

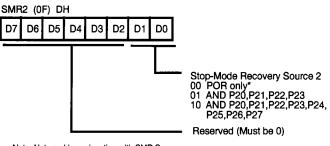
Low EMI Emission. The Z86C33/43 can be programmed to operate in a low EMI emission mode in the PCON register. The oscillator and all I/O ports can be programmed as low EMI emission mode independently. Use of this feature results in:

- The pre-drivers slew rate reduced to 10 ns typical.
- Low EMI output drivers have resistance of 200 Ohms (typical).
- Low EMI Oscillator
- Internal SCLK/TCLK= XTAL operation limited to a maximum of 4 MHz - 250 ns cycle time, when Low EMI Oscillator is selected and system clock (SCLK = XTAL, SMR Reg. Bit D1 =1).

Stop-Mode Recovery Register (SMR). This register selects the clock divide value and determines the mode of Stop-Mode Recovery (Figure 26 and 27). All bits are Write Only, except bit 7 which is Read Only. Bit 7 is a flag bit that is hardware set on the condition of Stop recovery and reset by a power-on cycle. Bit 6 controls whether a low level or a high level is required from the recovery source. Bit 5 controls the reset delay after recovery. Bits 2, 3, and 4, or the SMR register, specify the source of the Stop-Mode Recovery signal. Bits 0 and 1 determine the time-out period of the WDT. The SMR is located in Bank F of the Expanded Register Group at address 0BH.

FUNCTIONAL DESCRIPTION (Continued)





Note: Not used in conjunction with SMR Source

Figure 27. Stop-Mode Recovery Register 2 (0F) DH: Write Only)

Note: Not used in conjunction with SMR2 Source

* Default setting after RESET. ** Default setting after RESET and STOP-Mode Recovery.

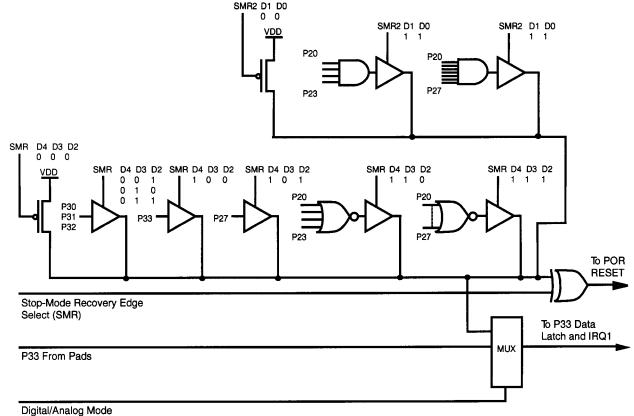
Figure 26. Stop-Mode Recovery Register (Write Only Except Bit D&, Which Is Read Only) SCLK/TCLK Divide-by-16 Select (D0). D0 of the SMR controls a divide-by-16 prescaler of SCLK/TCLK. The purpose of this control is to selectively reduce device power consumption during normal processor execution (SCLK control) and/or HALT Mode (where TCLK sources counter/timers and interrupt logic). This bit is reset to D0 = 0 after a Stop-Mode Recovery.

External Clock Divide-by-Two (D1). This bit can eliminate the oscillator divide-by-two circuitry. When this bit is 0, the System Clock (SCLK) and Timer Clock (TCLK) are equal to the external clock frequency divided by two. The SCLK/TCLK is equal to the external clock frequency when this bit is set (D1=1). Using this bit together with D7 of PCON further helps lower EMI (i.e., D7 (PCON) = 0, D1

(SMR) = 1). The default setting is zero. Maximum external clock frequency is 4 MHz when SMR Bit D1 = 1 where SCLK/TCLK = XTAL.

Stop-Mode Recovery Source (D2, D3, and D4). These three bits of the SMR specify the wake-up source of the STOP recovery (Figure 28 and Table 8). When the STOP-Mode Recovery Sources are selected in this register then SMR2 register bits D0, D1 must be set to zero.

Note: If the Port 2 pin is configured as an output, this output level will be read by the SMR circuitry.



Select (P3M)



Table 8. Stop-Mode Recovery Source

| SMR:432 | | 32 | Operation | |
|---------|----|----|-------------------------------------|--|
| D4 | D3 | D2 | Description of Action | |
| 0 | 0 | 0 | POR and/or external reset recovery | |
| 0 | 0 | 1 | P30 transition | |
| 0 | 1 | 0 | P31 transition (not in Analog Mode) | |
| 0 | 1 | 1 | P32 transition (not in Analog Mode) | |
| 1 | 0 | 0 | P33 transition (not in Analog Mode) | |
| 1 | 0 | 1 | P27 transition | |
| 1 | 1 | 0 | Logical NOR of P20 through P23 | |
| 1 | 1 | 1 | Logical NOR of P20 through P27 | |

Stop-Mode Recovery Delay Select (D5). This bit, if High, enables the TPOR /RESET delay after Stop-Mode Recovery. The default configuration of this bit is 1. If the "fast" wake up is selected, the Stop-Mode Recovery source must be kept active for at least 5 TpC.

Stop-Mode Recovery Edge Select (D6). A 1 in this bit position indicates that a high level on any one of the recovery sources wakes the Z86C33/43 from STOP Mode. A 0 indicates low-level recovery. The default is 0 on POR (Figure 27). This bit is used for either SMR or SMR2.

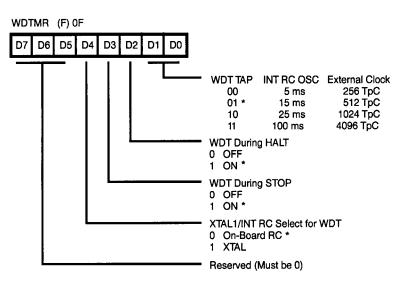
Cold or Warm Start (D7). This bit is set by the device upon entering STOP Mode. A 0 in this bit (cold) indicates that the device resets by POR/WDT RESET. A 1 in this bit (warm) indicates that the device awakens by a Stop-Mode Recovery source. Note: If the Port 2 pin is configured as an output, this output level will be read by the SMR2 circuitry. **Stop-Mode Recovery Register 2 (SMR2).** This register contains additional Stop-Mode Recovery sources. When the Stop-Mode Recovery sources are selected in this register then SMR Register. Bits D2, D3, and D4 must be 0.

| SMR:10 | | Operation |
|--------|---|------------------------------------|
| D1 D0 | | Description of Action |
| 0 | 0 | POR and/or external reset recovery |
| 0 | 1 | Logical AND of P20 through P23 |
| 1 | 0 | Logical AND of P20 through P27 |

Watch-Dog Timer Mode Register (WDTMR). The WDT is a retriggerable one-shot timer that resets the Z8 if it reaches its terminal count. The WDT is initially enabled by executing the WDT instruction and refreshed on subsequent executions of the WDT instruction. The WDT circuit is driven by an on-board RC oscillator or external oscillator from the XTAL1 pin. The POR clock source is selected with bit 4 of the WDT register (Figure 29).

WDT instruction affects the Z (Zero), S (Sign), and V (Overflow) flags. The WDTMR must be written to within 64 internal system clocks. After that, the WDTMR is write protected.

Note: WDT time-out while in STOP-Mode will not reset SMR, PCON, WDTMR, P2M, P3M, Ports 2 & 3 Data Registers, but the POR delay counter will still be enabled even though the SMR stop delay is disabled.



Default setting after RESET

Figure 29. Watch-Dog Timer Mode Register (Write Only)

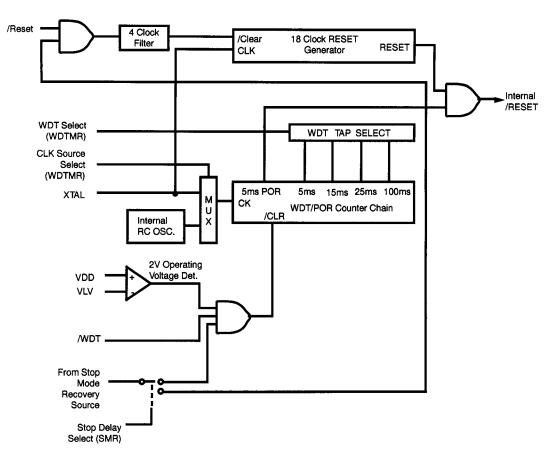


Figure 30. Resets and WDT

FUNCTIONAL DESCRIPTION (Continued)

WDT Time Select. (D0,D1). Selects the WDT time period and is configured as shown in Table 10.

| D1 | D0 | Timeout of Internal RC OSC | Timeout of System Clock |
|---------|------------|--|----------------------------|
| 0 | 0 | 3.5 ms min | 128 SCLK |
| 0 | 1 | 7 ms min | 256 SCLK |
| 1 | 0 | 14 ms min | 512 SCLK |
| 1 | 1 | 56 ms min | 2048 SCLK |
| The def | fault on i | i bus clock cycle reset is 15 ms. re for V _{CC} = 5.0V. | |

Table 10. WDT Time Select

WDTMR During HALT (D2). This bit determines whether or not the WDT is active during HALT Mode. A 1 indicates active during HALT. The default is 1.

WDTMR During STOP (D3). This bit determines whether or not the WDT is active during STOP Mode. Since XTAL clock is stopped during STOP Mode, the on-board RC must be selected as the clock source to the POR counter. A 1 indicates active during STOP. The default is 1.

Note: If permanent WDT is selected, the WDT will run in all modes and can not be stopped or disabled if the on board RC oscillator is selected as the clock source for WDT.

Clock Source for WDT (D4). This bit determines which oscillator source is used to clock the internal POR and WDT counter chain. If the bit is a 1, the internal RC oscillator is bypassed and the POR and WDT clock source is driven from the external pin, XTAL1. The default configuration of this bit is 0 which selects the Internal RC oscillator.

Note: The WDT can be permanently enabled (automatically enabled after reset) through a mask programming option. The option is selected by the customer at the time of ROM code submittal. In this mode, WDT is always activated when the device comes out of reset. Execution of the WDT instruction serves to refresh the WDT time-out period. WDT operation in the HALT and STOP Modes is controlled by WDTMR programming. If this mask option is not selected at the time of ROM code submission, the WDT must be activated by the user through the WDT instruction and is always disabled by any reset to the device.

read and is located in bank F of the Expanded Register

Group at address location 0FH (Figure 30).

Low Voltage Protection. An on-board Voltage Comparator checks that V_{CC} is at the required level to ensure correct operation of the device. Reset is globally driven if V_{CC} is below the specified voltage (Low Voltage Protection). The minimum operating voltage is varying with the temperature and operating frequency, while the Low Voltage Protection (V_{LV}) varies with temperature only.

The Low Voltage Protection trip voltage (V_{LV}) is less than 3V and above 1.4V under the following conditions.

Maximum (V_{LV}) Conditions:

| Case 1: | TA = -40°C, +105°C, Internal Clock | |
|---------|------------------------------------|--|
| | Frequency equal or less than 4 MHz | |
| Case 2: | TA = -40°C, +85°C, Internal Clock | |
| | Frequency equal or less than 6 MHz | |

Note: The internal clock frequency relationship to the XTAL clock is dependent on SMR Bit 0 1 setting.

The device functions normally at or above 3.0V under all conditions. Below 3.0V, the device functions normally until the Low Voltage Protection trip point (V_{LV}) is reached, for the temperatures and operating frequencies in Case 1 and Case 2, above. The device is guaranteed to function normally at supply voltages above the Low Voltage Protection trip point. The actual Low Voltage Protection trip point is a function of temperature and process parameters (Figure 32).

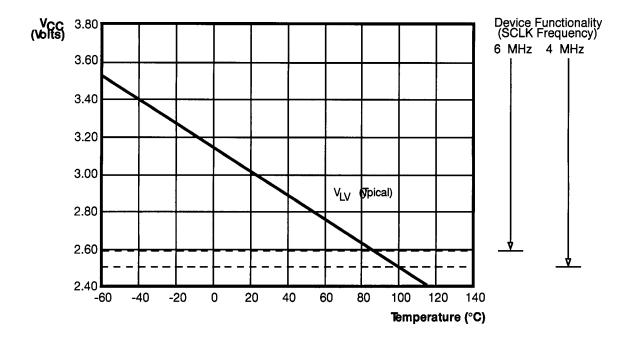
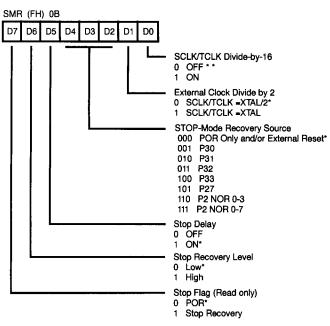


Figure 31. Typical Z86C33/43 Low Voltage Protection vs Temperature

EXPANDED REGISTER FILE CONTROL REGISTERS



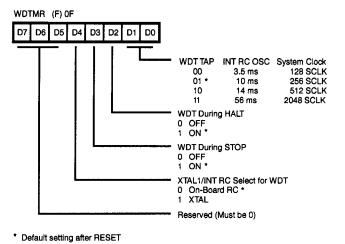
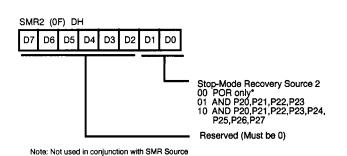


Figure 34. Watch-Dog Timer Mode Register (Write Only)

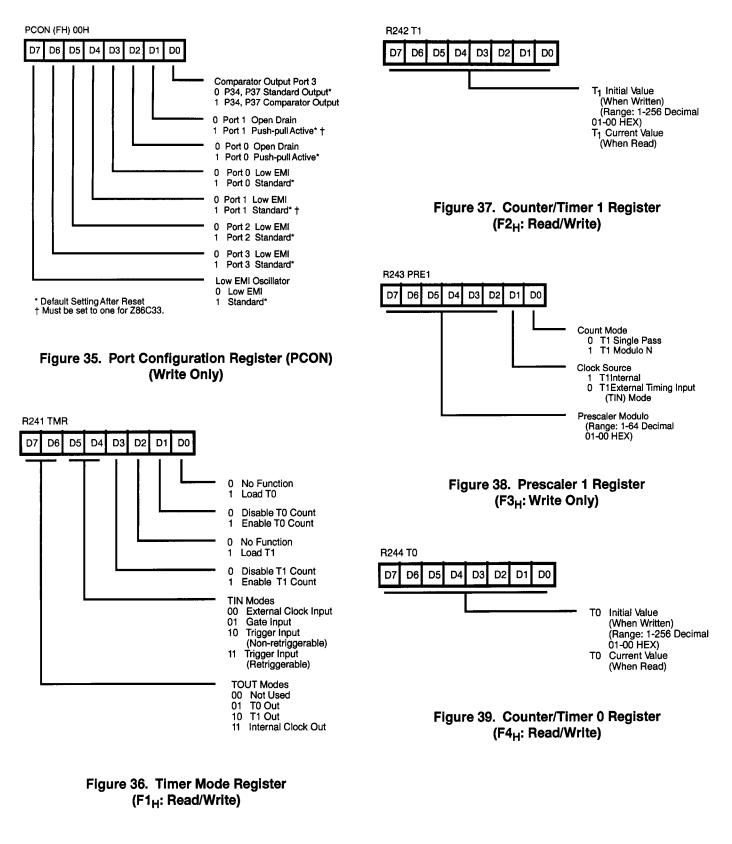
Note: Not used in conjunction with SMR2 Source * Default setting after RESET. * Default setting after RESET and STOP-Mode Recovery.

Figure 32. Stop-Mode Recovery Register (Write Only Except Bit D7, Which Is Read Only)

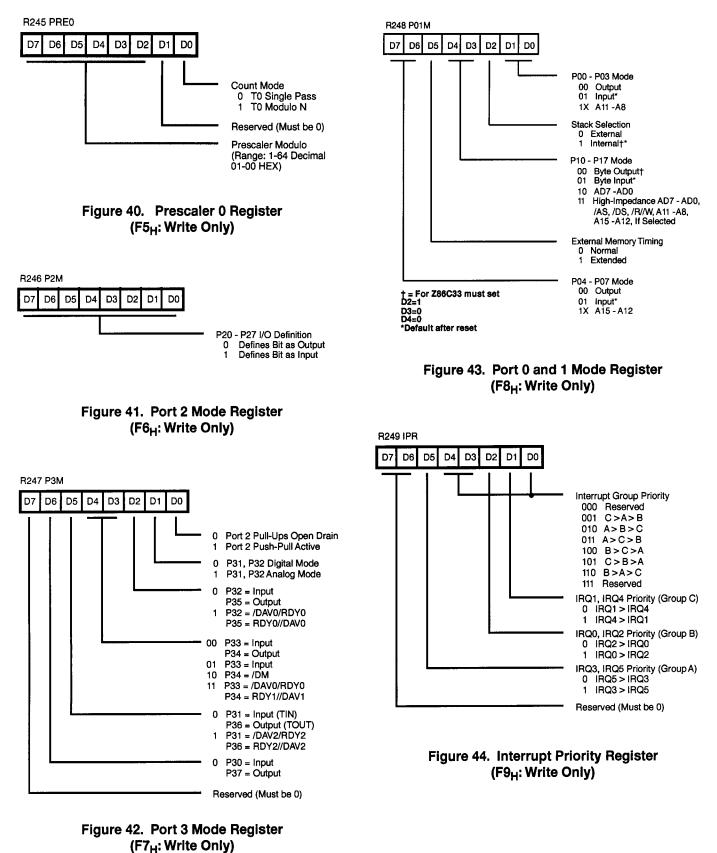


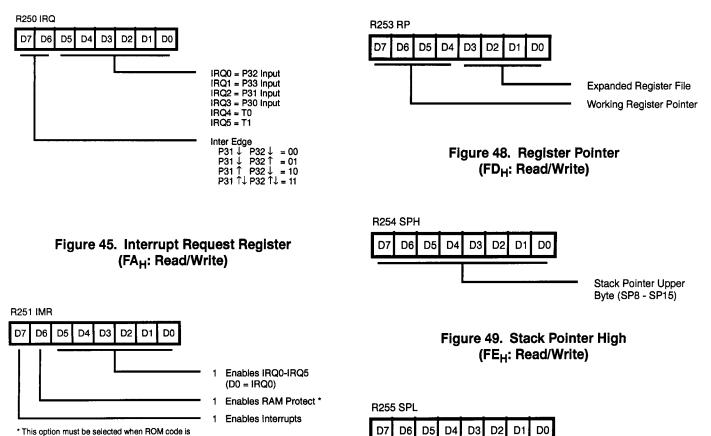


Z8 CONTROL REGISTERS



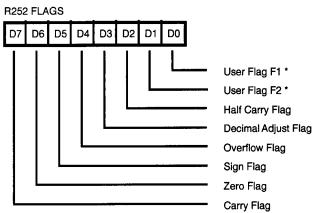
Z8 CONTROL REGISTERS (Continued)





 This option must be selected when ROM code is submitted for ROM Masking, otherwise this control bit is disabled permanently.

Figure 46. Interrupt Mask Register (FB_H: Read/Write)



* Not affected by reset

Figure 47. Flag Register (FC_H: Read/Write) Stack Pointer Lower Byte (SP0 - SP7)

Figure 50. Stack Pointer Low (FF_H: Read/Write)

PACKAGE INFORMATION

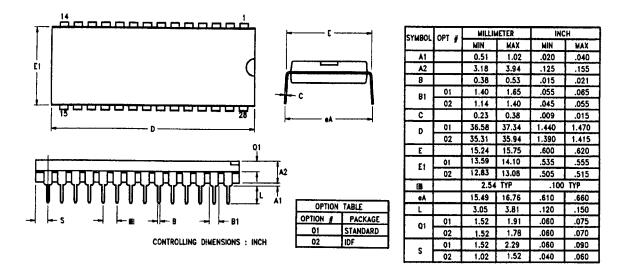


Figure 51. 28-Pin DIP Package Diagram

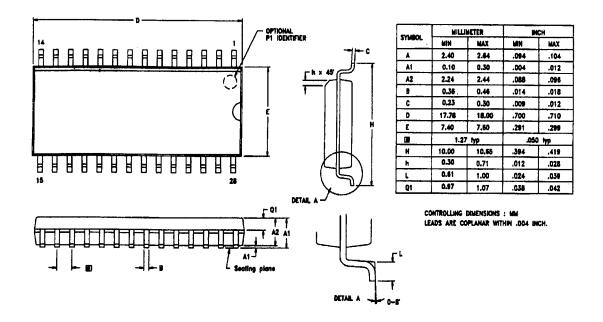


Figure 52. 28-Pin SOIC Package Diagram

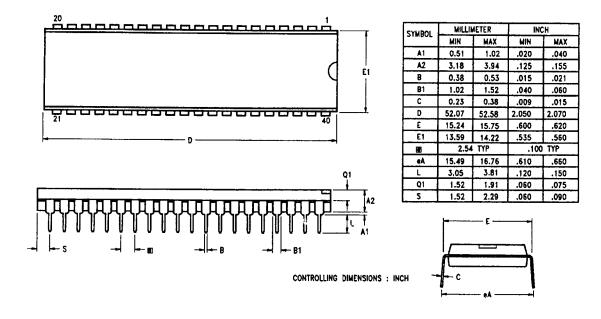


Figure 53. 40-Pin DIP Package Diagram

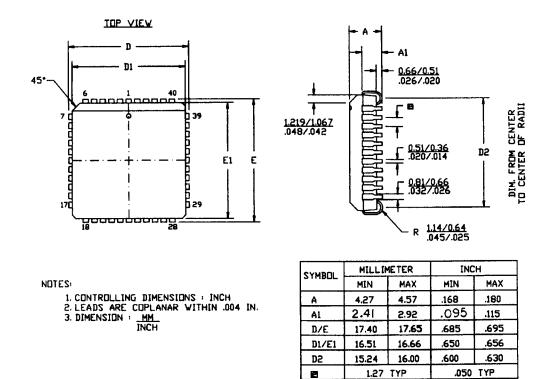


Figure 54. 44-Pin PLCC Package Diagram

1

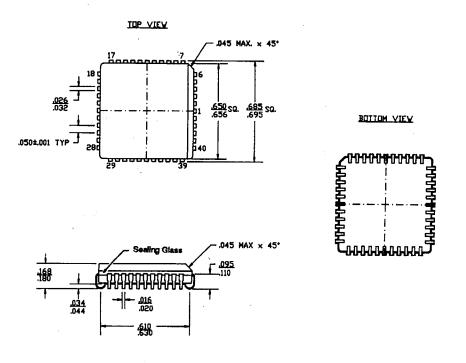


Figure 55. 44-Pin LQFP Package Diagram

ORDERING INFORMATION

Z86C33

| Standard To | emperature | Extended Temperature | | |
|----------------------------|----------------------------|----------------------------|----------------------------|--|
| 28-Pin DIP | 28-Pin SOIC | 28-Pin DIP | 28-Pin SOIC | |
| Z86C3316PSC Z86C3312PSC | Z86C3316SSC Z86C3312SSC | Z86C3316PEC Z86C3312PEC | Z86C3316SEC Z86C3312SEC | |
| | | | | |

Z86C43

CODES

| S | tandard Temperatu | re | Extended Temperature | | |
|-------------|-------------------|-------------|----------------------|-------------|-------------|
| 40-Pin DIP | 40-Pin PLCC | 44-Pin LQFP | 40-Pin DIP | 40-Pin PLCC | 44-Pin LQFP |
| Z86C4316PSC | Z86C4316VSC | Z86C4316FSC | Z86C4316PEC | Z86C4316VEC | Z86C4316FEC |
| Z86C4312PSC | Z86C4312VSC | Z86C4312FSC | Z86C4312PEC | Z86C4312VEC | Z86C4312FEC |

For fast results, contact your local Zilog sales office for assistance in ordering the part desired.

| CODES | |
|---|----------------------|
| Preferred Package | Longer Lead Time |
| P = Plastic DIP V = Plastic Chip Carrier | E = -40°C to +105°C |
| Longer Lead Time | Speeds |
| | 16 = 16 MHz |
| F = Plastic Quad Flat Pack | 12 = 12 MHz |
| S = Small Outline Integrated Chip T = PCB Chip Carrier | Environmental |
| Preferred Temperature | C = Plastic Standard |
| | |

 $S = 0^{\circ}C \text{ to } +70^{\circ}C$

Example: Z 86C43 16 P S C is a Z86C43, 16 MHz, DIP, 0° to +70°C, Plastic Standard Flow Environmental Flow Temperature Package Speed Product Number Zilog Prefix

Precautions

- 1. When in ROM Protect Mode, and executing out of External Program Memory, instructions LDC, LDCI, LDE, and LDEI cannot read Internal Program Memory
- 2. When in ROM Protect Mode, and executing out of Internal Program Memory, instructions LDC, LDCI, LDE, and LDEI can read Internal Program Memory.
- The device has an oscillator-free WDT reset for the device pins. When the device is reset from a WDT timeout, the reset will force the device pins to their reset default state even if the oscillator is not running.
- 4. The Port 3 outputs are reset to High State after Reset, except after Stop-Mode Recovery, at which time the outputs remain in the last state.
- 5. Extended timing is operable.
- 6. P0/P1/P2/P3 is Low-EMI software programmable.
- 7. P0/P1/P2 is software programmable for open-drain.
- 8. Expanded register PCON is Write-Only.
- 9. WDTMR is writeable only within the first 60 internal system clocks after Reset. Afterward, the WDTMR is write protected.

- 10. Device functions down to the V_{LV} threshold. At temperatures less than 25°C, the V_{LV} threshold will rise to a maximum V_{DD} of 3.6V.
- 11. Low-EMI is 25 percent of standard pull-down output driver, and 25 percent of standard pull-up output driver.
- 12. There is no clock filter on Reset pin.
- 13. Registers FE Hex (SPH) and FF Hex (SPL) are set to 00 Hex after any reset.
- 14. When Low EMI OSC is selected (PCON Reg Bit D7=0), the output drive of /DS, /AS, and R//W will also be in Low-EMI Mode.
- 15. P01M Reg Bit D4, D3 must be set to 00 Hex for Z86C33.
- 16. Must add a two NOP delay after selecting the P3M bit D1 to 1 before the comparitor output is valid. IRQ0, IRQ1, and IRQ2 should be cleared in IRQ register when the comparitor is enabled or disabled to avoid spurious noise creating a false interrupt.

Pre-Characterization Product:

The product represented by this CPS is newly introduced and Zilog has not completed the full characterization of the product. The CPS states what Zilog knows about this product at this time, but additional features or nonconformance with some aspects of the CPS may be found, either by Zilog or its customers in the course of further application and characterization work. In addition, Zilog cautions that delivery may be uncertain at times, due to start-up yield issues.

Customer Support

For answers to technical questions about the product, documentation, or any other issues with Zilog's offerings, please visit Zilog's Knowledge Base at <u>http://www.zilog.com/kb</u>.

For any comments, detail technical questions, or reporting problems, please visit Zilog's Technical Support at <u>http://support.zilog.com</u>.